# Goal-directed proofs and diagrams suitable for applications in philosophy of science

Aleksandra Samonek

Université catholique de Louvain Uniwersytet Jagielloński

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Thus, we can start applying goal-directed proof theory to philosophy of science.

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**Result:** the consequence operation may be non-Tarskian, where Tarskian consequence operation  $\vdash$  is:

- reflexive  $(A \vdash A)$ ,
- transitive (if  $\Gamma \vdash B$  and  $\Delta \cup \{B\} \vdash A$ , then  $\Gamma \cup \Delta \vdash A$ ),
- monotonic (if  $\Gamma \vdash A$ , then  $\Gamma \cup \Delta \vdash A$ ).

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- if the question ?A cannot be answered directly, obtain partial questions and proceed to answer ?A indirectly.

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This new format aimed at making the search patch (heuristics) formally explicit.

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We focus on providing a reliable tool for making relevant inferences which can be used with ease and also giving the reasoner an enhanced understanding of the inference and the relation between the precedent and the consequent. This in turn leads to improving the strategies of our everyday reasoning.

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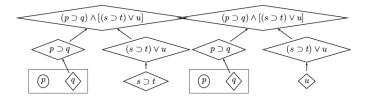
We have two options to do this.

Now, the leftmost diagram is continued by means of conditional proof: p is introduced as hypothesis and q forms the new subgoal.

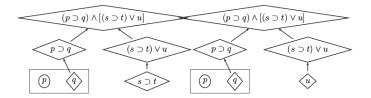
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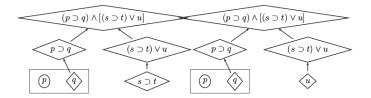


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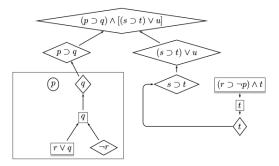
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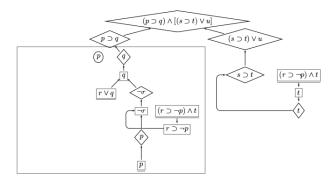


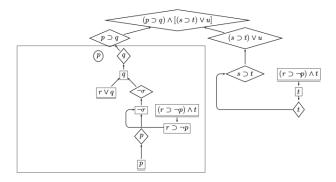
Since *u* is a variable that is not present in the premisses, no premise is relevant for its deduction. The diagram can therefore not be completed. We introduce premise  $((r \supset \neg p) \land t)$ , which grounds the rightmost part of the diagram. This part is now completed: We continue the conditional proof by introducing premise  $r \lor q$ , since it is relevant for deducing q. This implies that we have a new goal, namely  $\neg r$ .

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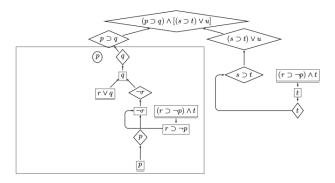


We continue our search for  $\neg r$  by means of premise  $(r \supset \neg p) \land t$ , via simplification.





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Note that we handled the two implications differently: one was grounded via a conditional proof, one via the grounding of the consequent.

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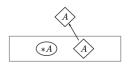
HYP allows us to write down a formula in a circular node; in doing so a new conditional proof is commenced in which the hypothesis may be used as an extra premise. The boundaries of the conditional proof are depicted by a box.

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### Reductio ad absurdum



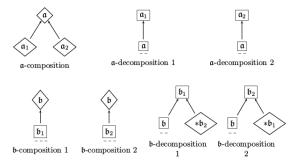
This allows us to ground any formula in a hypothesis consisting of its negation and itself. Given that the hypothesis functions as an extra premise inside the box, this means we can ground the formula if we can derive it from its negation.

### $\mathfrak a$ and $\mathfrak b$ rules

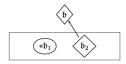
a	$\mathfrak{a}_1$	$\mathfrak{a}_2$	b	$\mathfrak{b}_1$	$\mathfrak{b}_2$
$A \wedge B$	Α	В	$\neg (A \land B)$	*A	*B
$\neg (A \lor B)$	*A	*B	$A \lor B$	A	В
$A \equiv B$	$A \supset B$	$B \supset A$	$\neg(A \equiv B)$	$\neg(A \supset B)$	$\neg(B\supset A)$
$\neg (A \supset B)$	Α	*B	$A \supset B$	*A	В

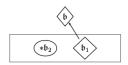
We use the following table to abbreviate formulas with the same meaning:

We use  $\ast \mathfrak{b}$  to denote the complement of  $\mathfrak{b}.$  We can define the rules as follows:



# Conditional proof



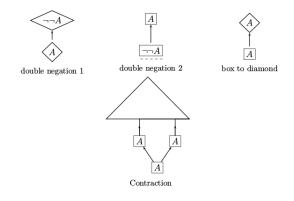


## Conditional proof

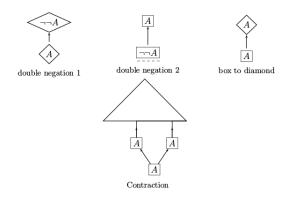


These rules allow us to ground a b-formula, such as an implication, in a hypothesis (the implicans) and the implicandum. The hypothesis functions as an extra premise in the entire box. Nodes that are part of the tree with the implicandum as root node also fall inside the box.

## Remaining rules

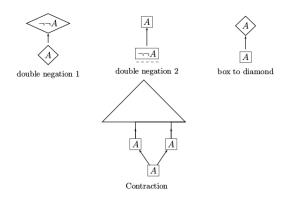


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- The contraction rule is expressed in a different way than the other rules. The triangle expresses that there is diagrammatic proof to which these nodes belong.

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Why? b-decomposition 2 cannot be applied to a diamond-shaped node here and so t cannot be deduced.

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- To reach their goal, Batens and Meheus push down the proof heuristics (algorithmic stage) into the rules of inference (mathematical stage), thus modifying the consequence operation.
- Our proof method allows human reasoners to use a specific proving method (without ECQs) without letting go of the Tarskian consequence operation in the *underlying* logic.

- Gabbay and Olivetti initiated goal-directed proof theory based on the distinction between the mathematical and the algorithmical stage of defining a logical system.
- Batens and Meheus developed a goal-directed proof theory aimed at human reasoning rather than automated proof analysis.
- To reach their goal, Batens and Meheus push down the proof heuristics (algorithmic stage) into the rules of inference (mathematical stage), thus modifying the consequence operation.
- Our proof method allows human reasoners to use a specific proving method (without ECQs) without letting go of the Tarskian consequence operation in the *underlying* logic.
- In this way, our approach is closer to the original motivations of Gabbay and Olivetti.

Thank you for your attention!

aleksandra.samonek@uclouvain.be