#### On Einstein Algebras and Relativistic Spacetimes

Sarita Rosenstock Thomas William Barrett James Owen Weatherall

University of California, Irvine Department of Logic and Philosophy of Science

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Criterion: Theories  $T_1$  and  $T_2$  are **equivalent** if the category  $C_1$  of models of  $T_1$  is either equivalent *or dual* to the category  $C_2$  of models of  $T_2$ .



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#### 1 Category of Relativistic Spacetimes (GR)

#### **2** Category of Einstein Algebras (EA)

Smooth Algebras Duality of **SmoothMan** and **SmoothAlg** Metrics on Smooth Algebras

3 Duality of GR and EA

**4** Concluding Remarks

## Category of Relativistic Spacetimes (GR)

Objects: (M, g)Arrows: Isometric embeddings: smooth maps  $\varphi : (M, g) \rightarrow (M', g')$ s.t.  $\varphi^*(g') = g$ 

- An *algebra A* is a real vector space with a commutative, associative product and a multiplicative identity.
- An *(algebra) homomorphism* is a map between algebras that preserves the vector space operations, product, and multiplicative identity.
- |*A*| denotes the collection of homomorphisms from *A* to ℝ, called the *points* of *A*.

• A is geometric if  $\bigcap_{p \in |A|} \ker(p) = \{\mathbf{0}\}.$ 

•  $\tilde{A} = \{\tilde{f} : |A| \to \mathbb{R} \mid \exists f \in A \text{ s.t. } \tilde{f}(x) = x(f) \forall x \in |A| \}$ • Operations on  $\tilde{A}$ :

$$(\tilde{f} + \alpha \tilde{g})(x) = \tilde{f}(x) + \alpha \tilde{g}(x) = x(f) + \alpha x(g)$$
$$(\tilde{f} \cdot \tilde{g})(x) = \tilde{f}(x) \cdot \tilde{g}(x) = x(f) \cdot g(f)$$

• A geometric  $\Rightarrow \tau : A \rightarrow \tilde{A}$  as  $f \mapsto \tilde{f}$  is an isomorphism.

 The weak topology on |A| is the coarsest topology on |A| s.t. every *f̃* ∈ *Ã* ≅ A is continuous.

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 Given alg. homomorphism ψ : A → B, the map |ψ| : |B| → |A| as x ↦ x ∘ ψ is continuous in the weak topology.

- A is complete if for every function f : |A| → ℝ which is s.t. for every p ∈ |A| there is a neighborhood O of p in |A| and an element f ∈ A such that f ↾<sub>O</sub> ≡ f ↾<sub>O</sub> , f ∈ Ã ≅ A.
- A smooth algebra is a complete, geometric algebra with a countable open covering {U<sub>k</sub>} s.t. each U<sub>k</sub> is isomorphic to a subset of C<sup>∞</sup>(ℝ<sup>n</sup>).

• *n* is the *dimension* of *A*.

#### F: SmoothMan $\rightarrow$ SmoothAlg

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- Given a smooth manifold M,  $F(M) = C^{\infty}(M)$ .
- Given a smooth map  $\varphi: M \to N$ ,  $F(\varphi)$  is the map  $\hat{\varphi}: C^{\infty}(N) \to C^{\infty}(M)$  as  $\hat{\varphi}(f) = f \circ \varphi$  for any  $f \in C^{\infty}(N)$ .

## $G: \textbf{SmoothAlg} \rightarrow \textbf{SmoothMan}$

- Given a smooth algebra A, G(A) = |A|, with charts given by smoothness structure of A.
- Given an algebra homomorphism  $\psi : A \to B$ ,  $G(\psi)$  is the map  $|\psi| : |B| \to |A|$  between the manifolds G(B) and G(A).

• Correspondence  $heta: M o G \circ F(M) = |C^{\infty}(M)|$  as

$$\theta(p)(f)=f(p)$$

for all  $p \in M$ ,  $f \in C^{\infty}(M)$ .

• Correspondence  $\eta: A o F \circ G(A) = C^\infty(|A|)$  as

 $\eta(f)(p) = p(f)$ 

for all  $f \in A$ ,  $p \in |A|$ .

# Theorem **SmoothMan** and **SmoothAlg** are dual.

Idea: F and G are contravariant functors and "up to isomorphism" inverses of one another.

Upshot:

$$A \leftrightarrow G(A) = |A|$$
  

$$M \leftrightarrow F(M) = C^{\infty}(M)$$
  

$$\psi : A \to B \leftrightarrow G(\psi) = |\psi| : |B| \to |A|$$
  

$$\varphi : M \to N \leftrightarrow F(\varphi) = |\hat{\varphi}| : C^{\infty}(N) \to C^{\infty}(M)$$

#### Derivations on Smooth Algebras

• A derivation on A is an  $\mathbb{R}$ -linear map  $\hat{X} : A \to A$  that satisfies the Leibniz rule,

$$\hat{X}(fg) = f\hat{X}(g) + g\hat{X}(f) \quad \forall f,g \in A.$$

Derivations at a point:

$$\hat{X}_{p}: A 
ightarrow \mathbb{R}$$
 as  $\hat{X}_{p}(f) = \hat{X}(f)(p)$ 

• Correspond to vector fields X on G(A) = |A| as

$$\hat{X}_p(f) = X_p(f)$$

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for  $f \in \tilde{A} \cong A$  and  $p \in |A|$ .

## Metrics on Smooth Algebras

- The space of derivations on A is a module Γ(A) over A, with dual module Γ\*(A).
- A metric on A is a module isomorphism  $\hat{g} : \Gamma(A) \to \Gamma^*(A)$  s.t.  $\hat{g}(\hat{X})(\hat{Y}) = \hat{g}(\hat{Y})(\hat{X})$  for all  $\hat{X}, \hat{Y} \in \Gamma(A)$ .
- The signature of  $\hat{g}$  is the pair (m, n m), where m is unique s.t. there exists a basis  $\xi_1, \ldots, \xi_n$  for the tangent space  $T_pA$  such that

$$egin{array}{rll} \hat{g}(\xi_i,\xi_i)&=&+1& ext{if}&1\leq i\leq m\ \hat{g}(\xi_j,\xi_j)&=&-1& ext{if}&m< j\leq n\ \hat{g}(\xi_i,\xi_j)&=&0& ext{if}&i
eq j \end{array}$$

#### Definition

An *Einstein algebra* is a pair  $(A, \hat{g})$  where A is a smooth algebra and  $\hat{g}$  is a (1, n - 1) metric on A.

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## Category of Einstein Algebras (EA)

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- **Objects:** Einstein algebras  $(A, \hat{g})$
- Arrows: Smooth algebra homomorphisms that preserve the metric.

#### Lemma

## $J: \mathbf{GR} \to \mathbf{EA}$

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- $J(M,g) = (C^{\infty}(M), \hat{g})$ , where  $\hat{g}$  is given by Lemma.
- Given an isometric embedding arphi:(M,g)
  ightarrow(M',g'),

$$J(\varphi) = F(\varphi) = \hat{\varphi} : C^{\infty}(M') \to C^{\infty}(M).$$

### $K : \mathbf{EA} \to \mathbf{GR}$

- $K(A, \hat{g}) = (|A|, |\hat{g}|)$ , where  $|\hat{g}|$  is given by Lemma.
- Given an EA homomorphism  $\psi: (A, \hat{g}) 
  ightarrow (A', \hat{g}')$ ,

$$K(\psi) = G(\psi) = |\psi| : |A'| \to |A|.$$

Theorem The categories **EA** and **GR** are dual

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Idea: J and K are contravariant functors and "up to isomorphism" inverses of one another.

Upshot:

$$(A, \hat{g}) \leftrightarrow K(A, \hat{g}) = (|A|, \hat{g})$$
  

$$(M, g) \leftrightarrow J(M, g) = (C^{\infty}(M), \hat{g})$$
  

$$\psi : (A, \hat{g}) \rightarrow (B, \hat{g}') \leftrightarrow K(\psi) = |\psi| : (|B|, |\hat{g}'|) \rightarrow (|A|, |\hat{g}|)$$
  

$$\varphi : (M, g) \rightarrow (N, g') \leftrightarrow J(\varphi) = |\hat{\varphi}| : (C^{\infty}(N), \hat{g}') \rightarrow (C^{\infty}(M), \hat{g})$$

## Overview

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- Criterion of theoretical equivalence that allows for categorical duality.
- Case Study: Einstein algebras and relativistic spacetimes.
- Claim: Duality of **EA** and **GR** shows how they are empirically equivalent.

Thank you.