

# Operationalization of relativistic energy, momentum and inertial mass

Bruno Hartmann (Humboldt Univ.)

LRB'15, Budapest 12.08.2015

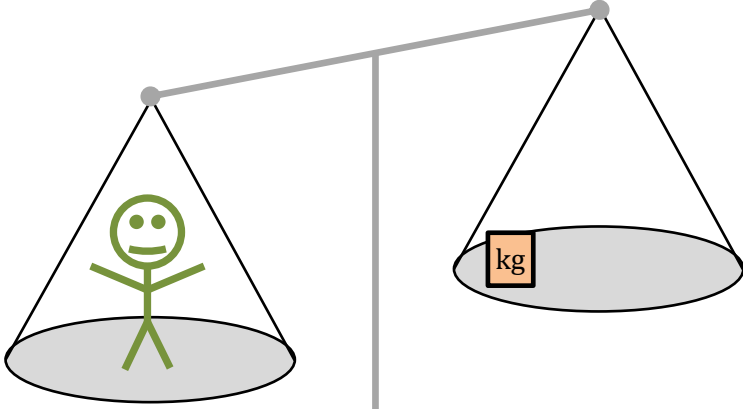
# Basic Measurement

$\rangle_l$

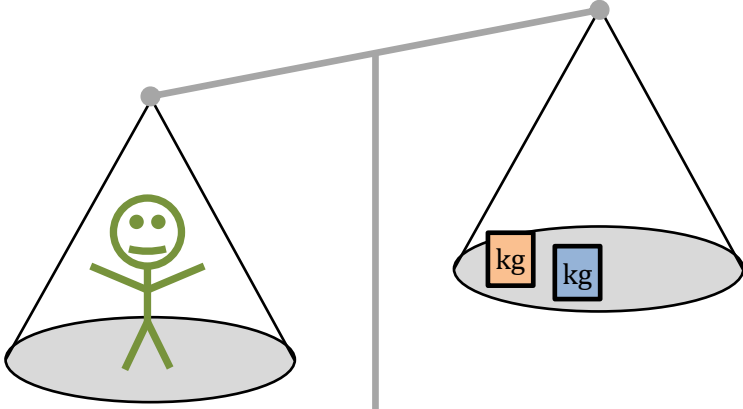
$\rangle_m$

$\rangle_p$

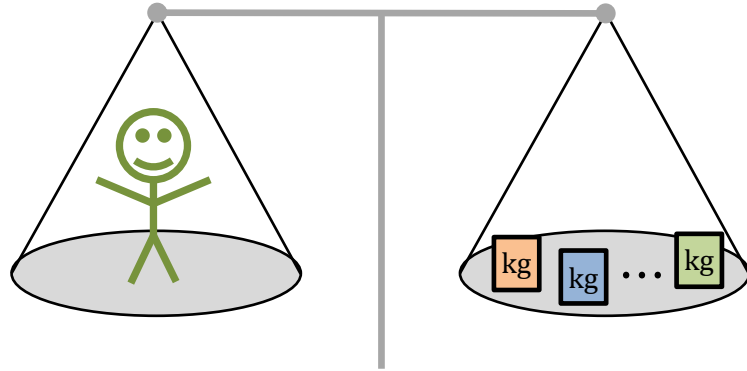
# Basic Measurement



# Basic Measurement



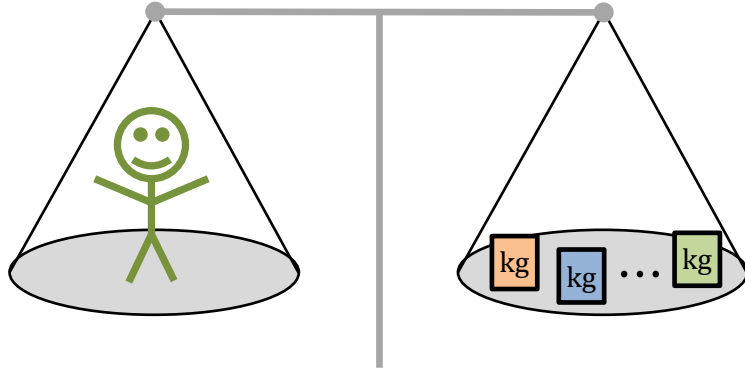
# Basic Measurement



arithmetic formulation

$$m[\text{stick figure}] = 1\text{kg} + 1\text{kg} + \dots$$

# Basic Measurement



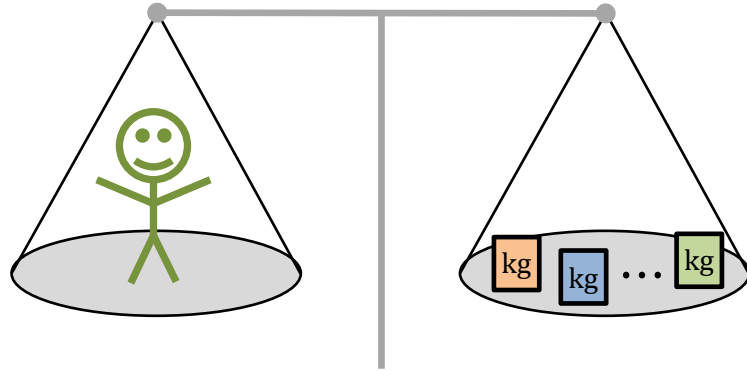
arithmetic formulation

$$m[\text{stick figure}] = 1\text{kg} + 1\text{kg} + \dots$$

physical operations

$$>_m \quad *_m$$

# Basic Measurement



arithmetic formulation

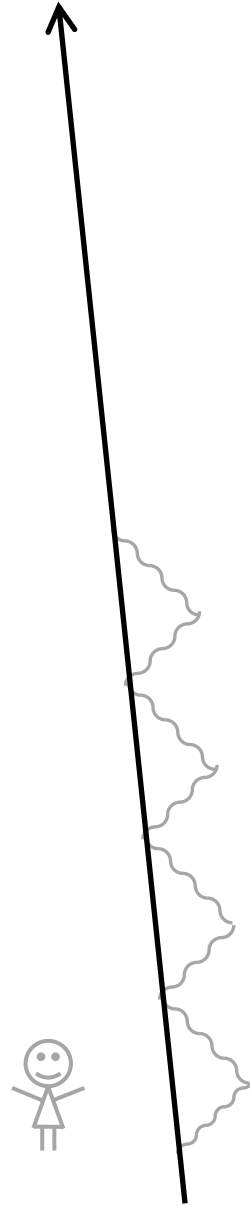
$$m[\text{stick figure}] = 1\text{kg} + 1\text{kg} + \dots \quad 1\text{m} + 1\text{m} \quad 1\text{s} + 1\text{s}$$

physical operations

$$>_m \quad *_m$$

# Kinematics

$\gamma_{t,s}$



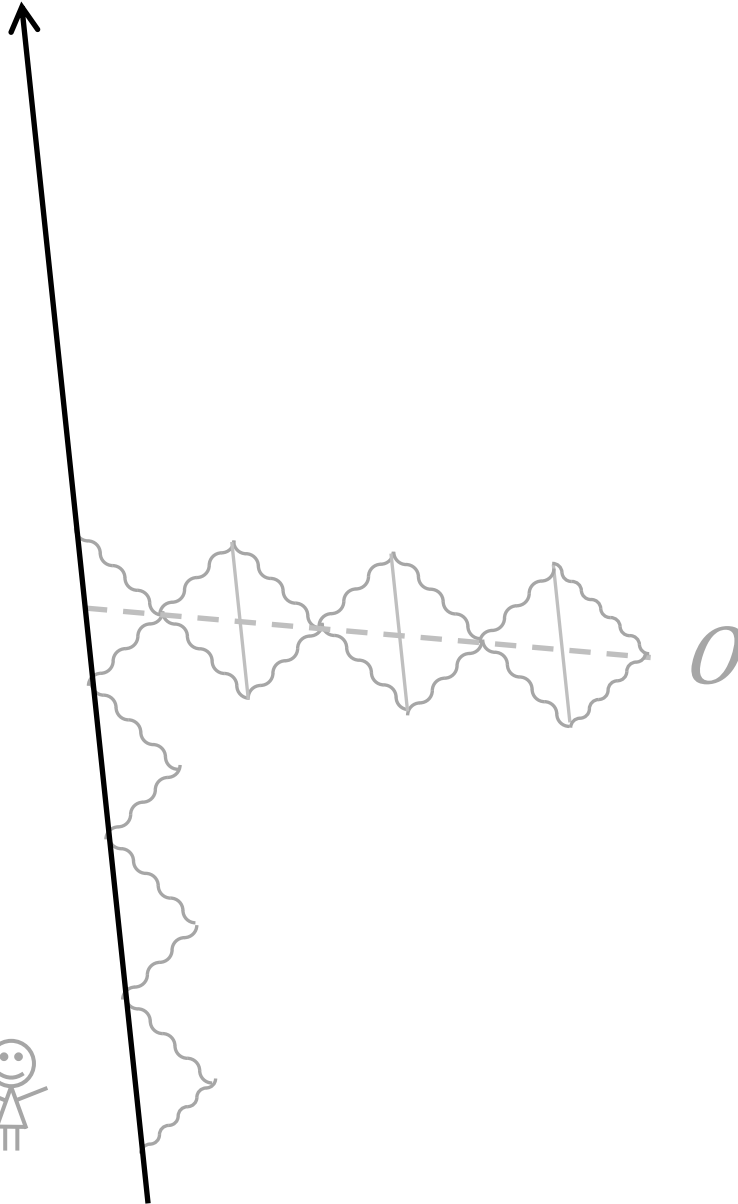
$0$



# Kinematics

$\gamma_{t,s}$

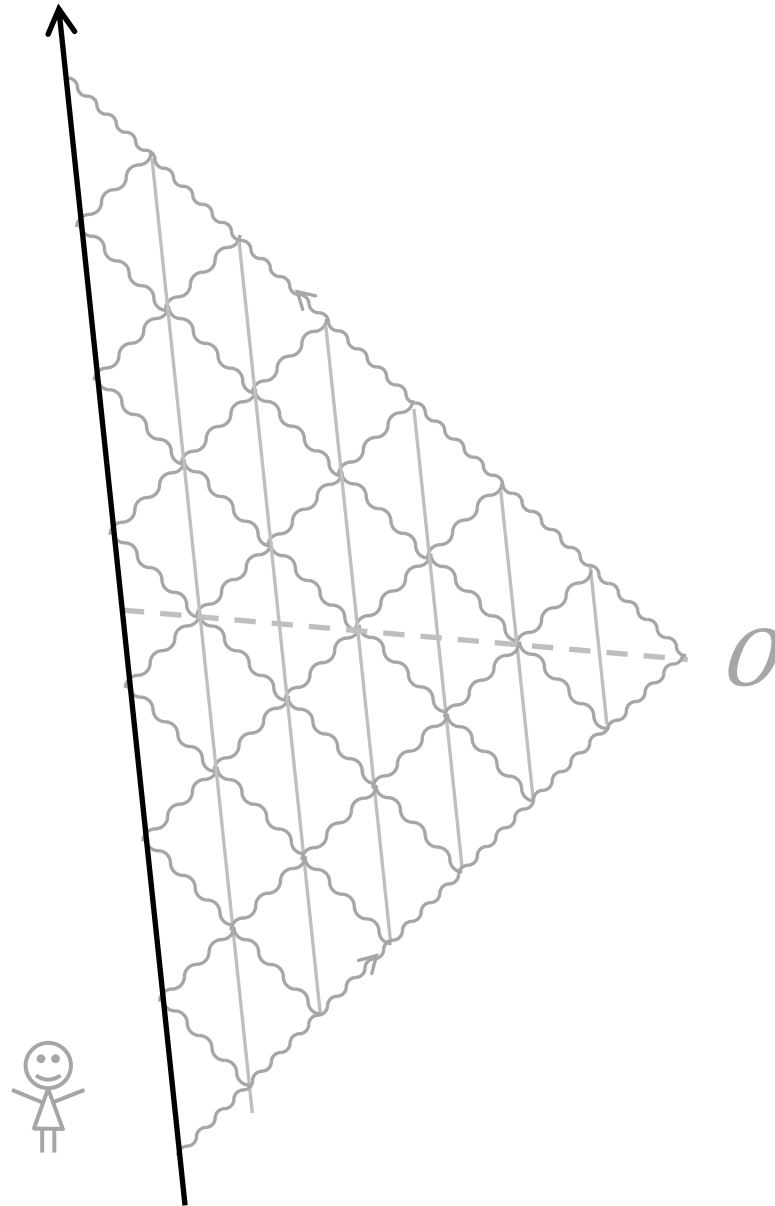
$L * \dots * L$



# Kinematics

$\succ_{t,s}$

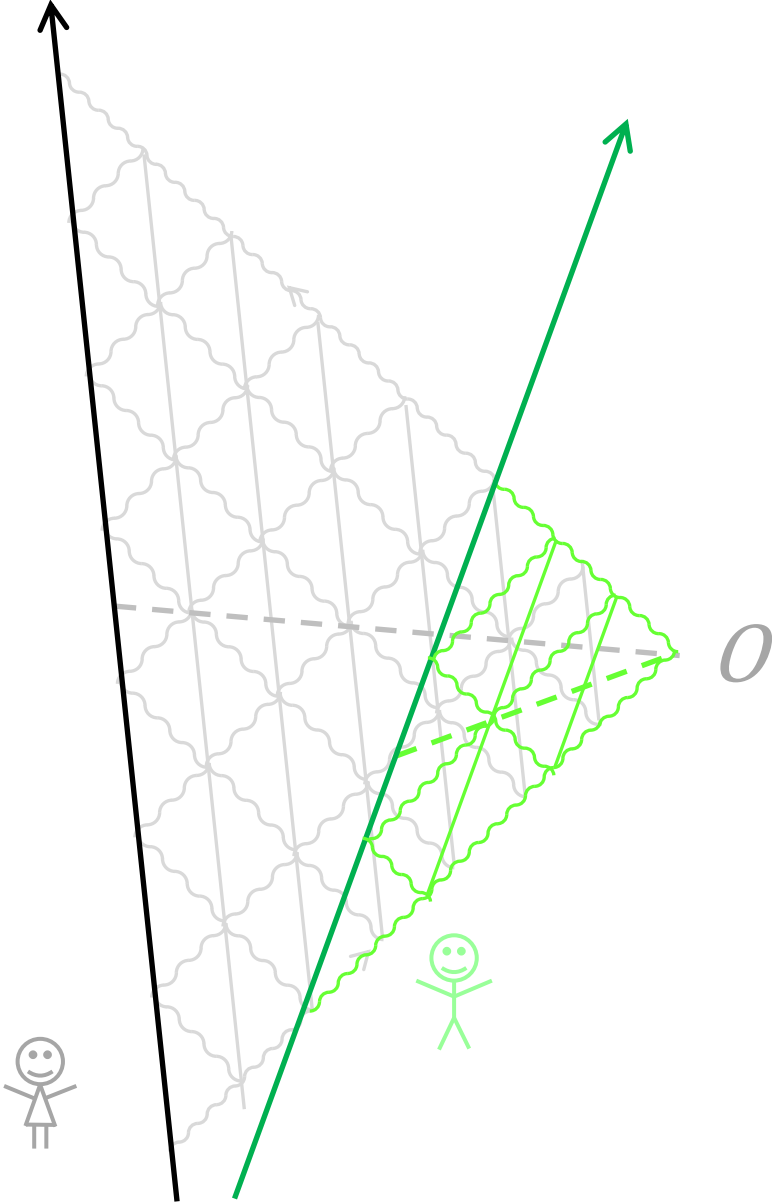
$L * \dots * L$



# Kinematics

$\succ_{t,s}$

$L * \dots * L$



# Dynamics

Dynamics

Hertz outline

energy as basic observable

# Dynamics

## Hertz outline

energy as basic observable

define elementary comparison  $>_E$  (Leibniz)

basic measurement  $*_E$  (Helmholtz)

# Dynamics

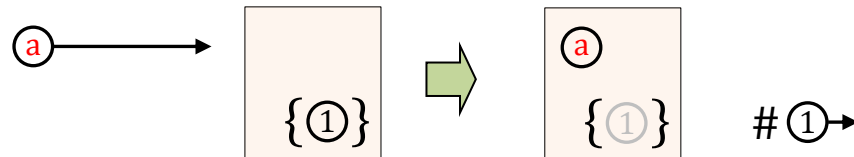
## Hertz outline

energy as basic observable

define elementary comparison  $>_E$  (Leibniz)

basic measurement  $*_E$  (Helmholtz)

## material model



# Dynamics

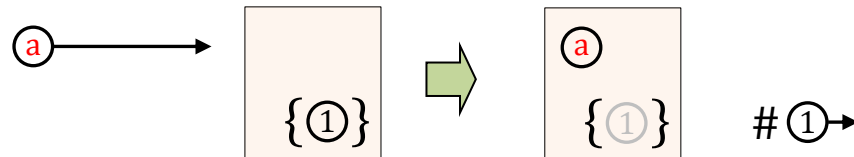
## Hertz outline

energy as basic observable

define elementary comparison  $>_E$  (Leibniz)

basic measurement  $*_E$  (Helmholtz)

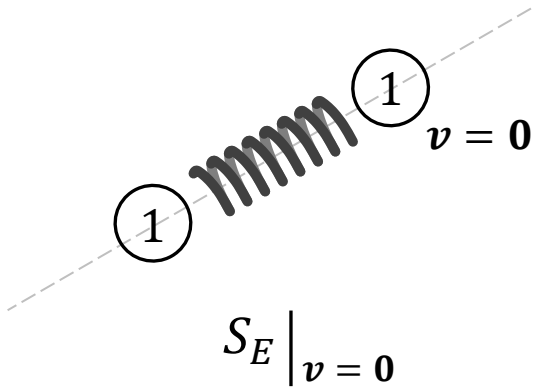
## material model



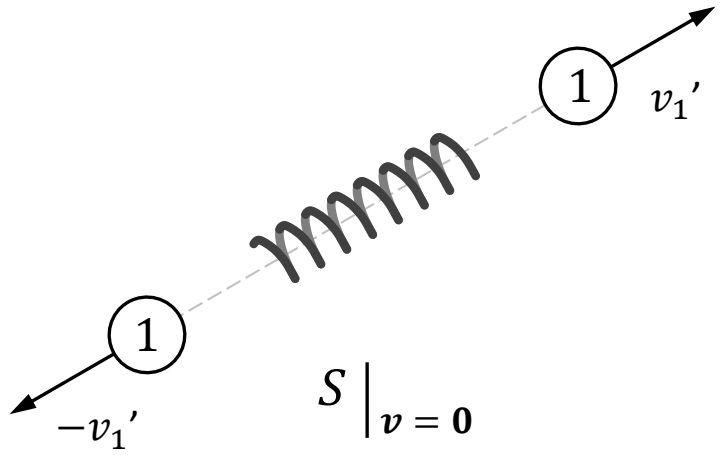
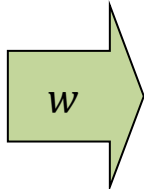
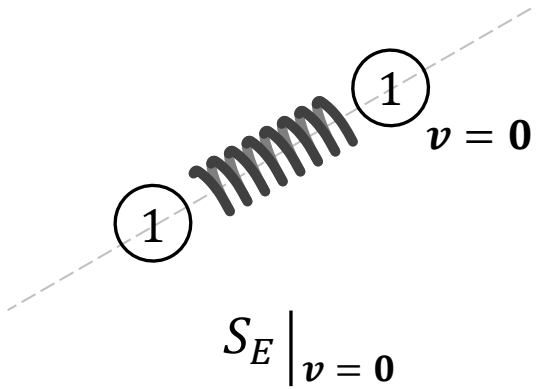
## abstract physical perspective



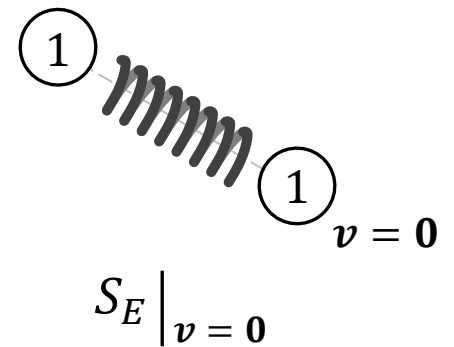
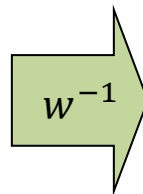
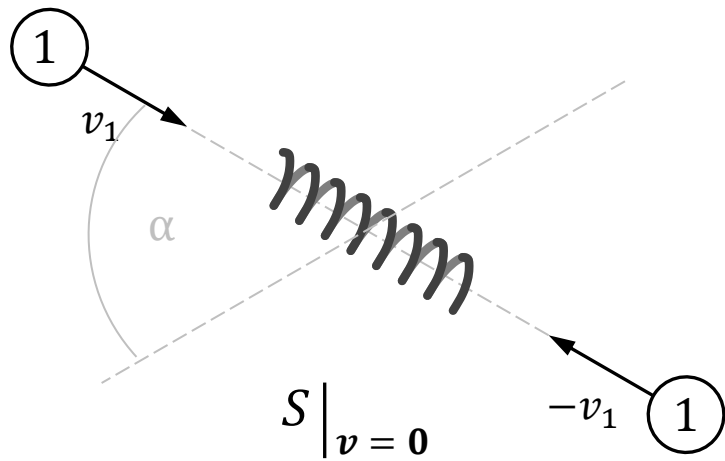
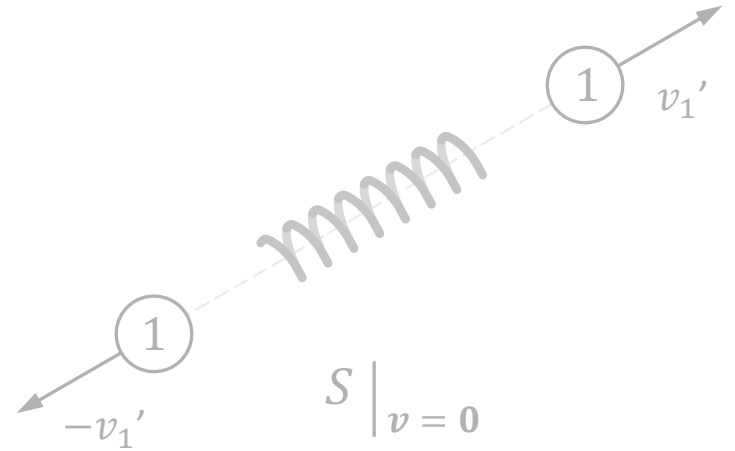
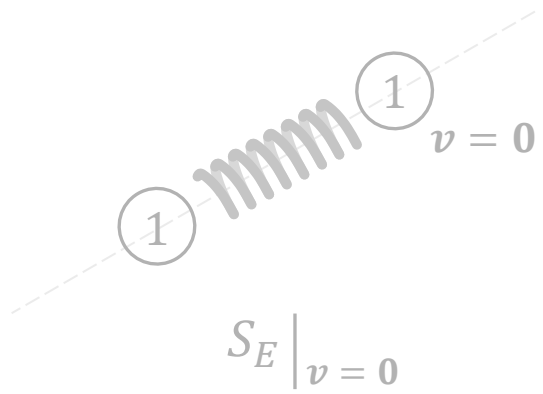
# Reference Process



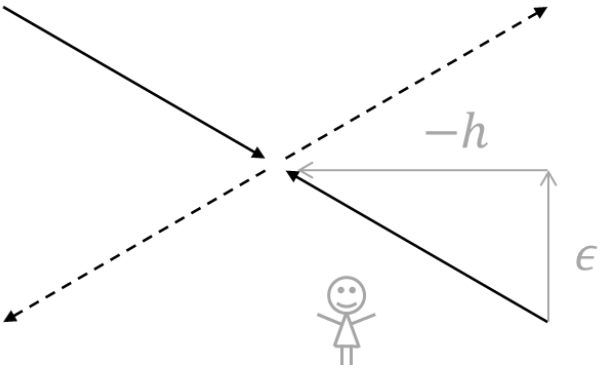
# Reference Process



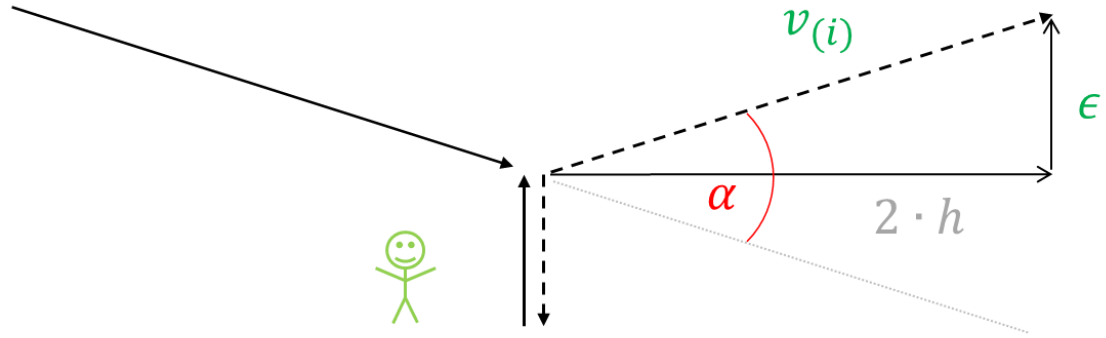
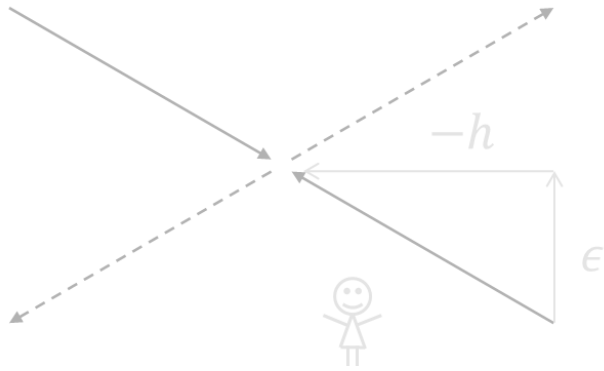
# Reference Process



# Eccentric Elastic Collision



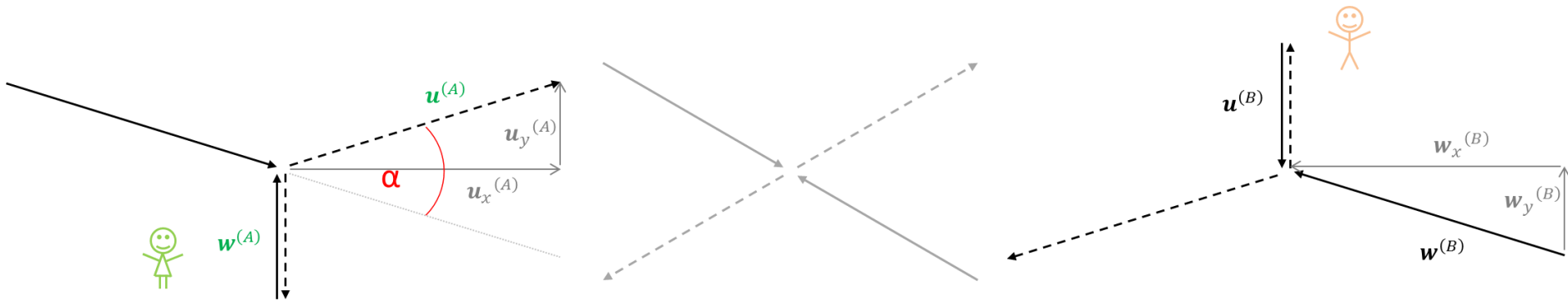
# Eccentric Elastic Collision



Transversal Kick

$$\sin \frac{\alpha}{2} = \frac{\epsilon}{v}$$

# Eccentric Elastic Collision



## Transversal Kick

$$\sin \frac{\alpha}{2} = \frac{\sqrt{1 - \frac{v_x^2}{c^2}}}{v} \cdot w$$

# Assemble Calorimeter

inelastic collision

$w_1$



# Assemble Calorimeter

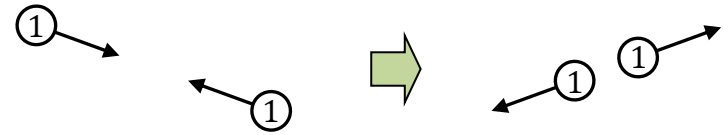
inelastic collision

$$w_1$$



eccentric elastic collision

$$w_1^{-1} * w_1$$





# Assemble Calorimeter

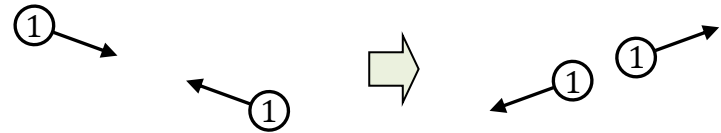
inelastic collision

$$w_1$$



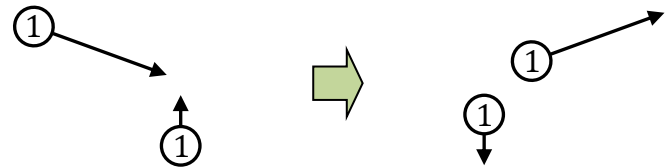
eccentric elastic collision

$$w_1^{-1} * w_1$$



transversal kick

$$w_T := (w_1^{-1} * w_1)^{(B)}$$



# Assemble Calorimeter

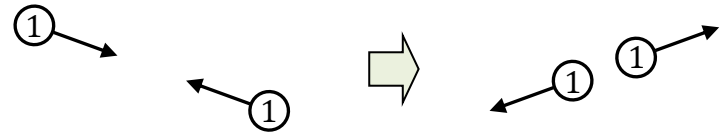
inelastic collision

$$W_1$$



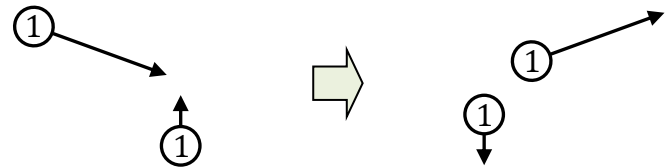
eccentric elastic collision

$$W_1^{-1} * W_1$$



transversal kick

$$W_T := (W_1^{-1} * W_1)^{(B)}$$



generic head-on collision

$$W_H := W_T * \dots * W_T$$



# Assemble Calorimeter

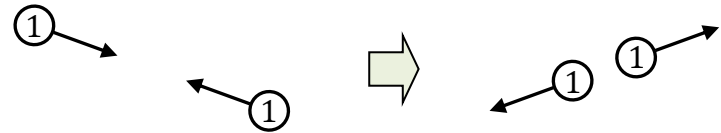
inelastic collision

$$w_1$$



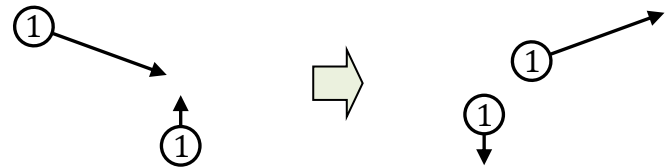
eccentric elastic collision

$$w_1^{-1} * w_1$$



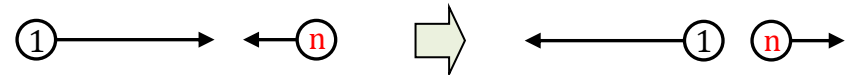
transversal kick

$$w_T := (w_1^{-1} * w_1)^{(B)}$$



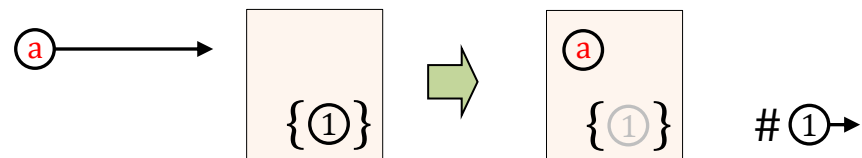
generic head-on collision

$$w_H := w_T * \dots * w_T$$



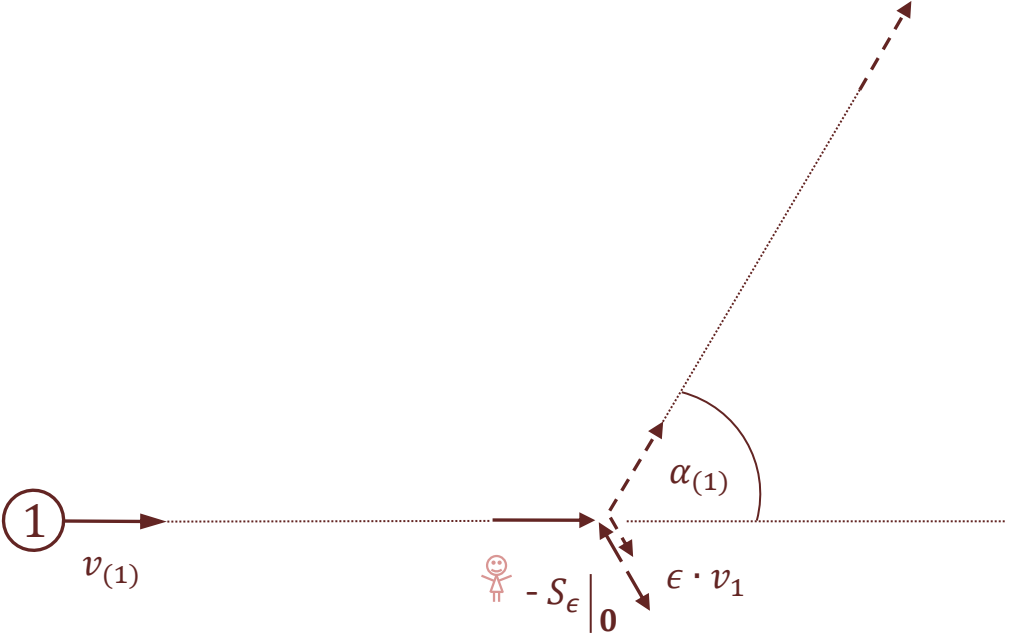
absorption in calorimeter

$$w_{\text{cal}} := w_L^{(A)} * w_L^{(B)} * \dots$$



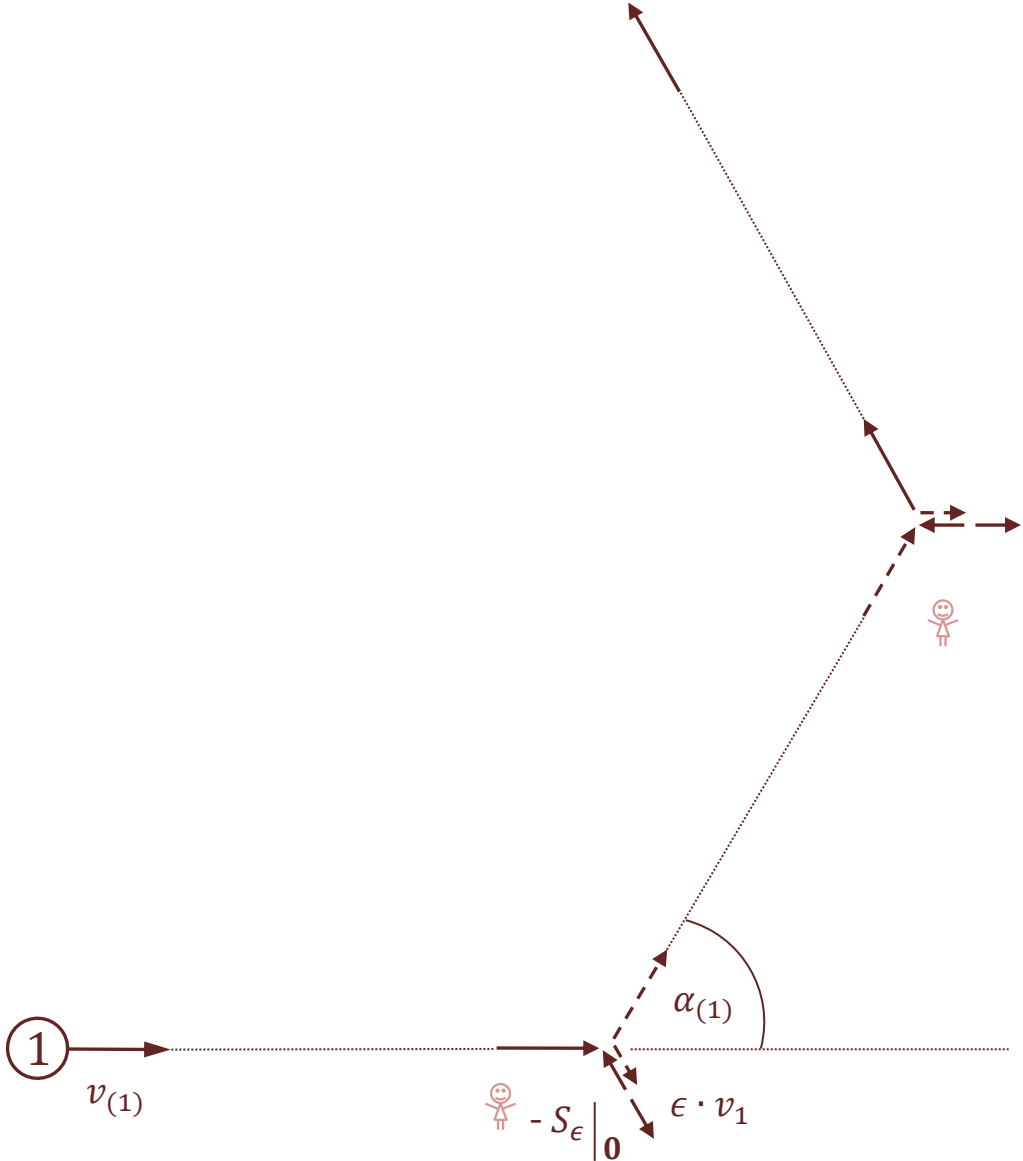
# Reversion Process

$W_T$

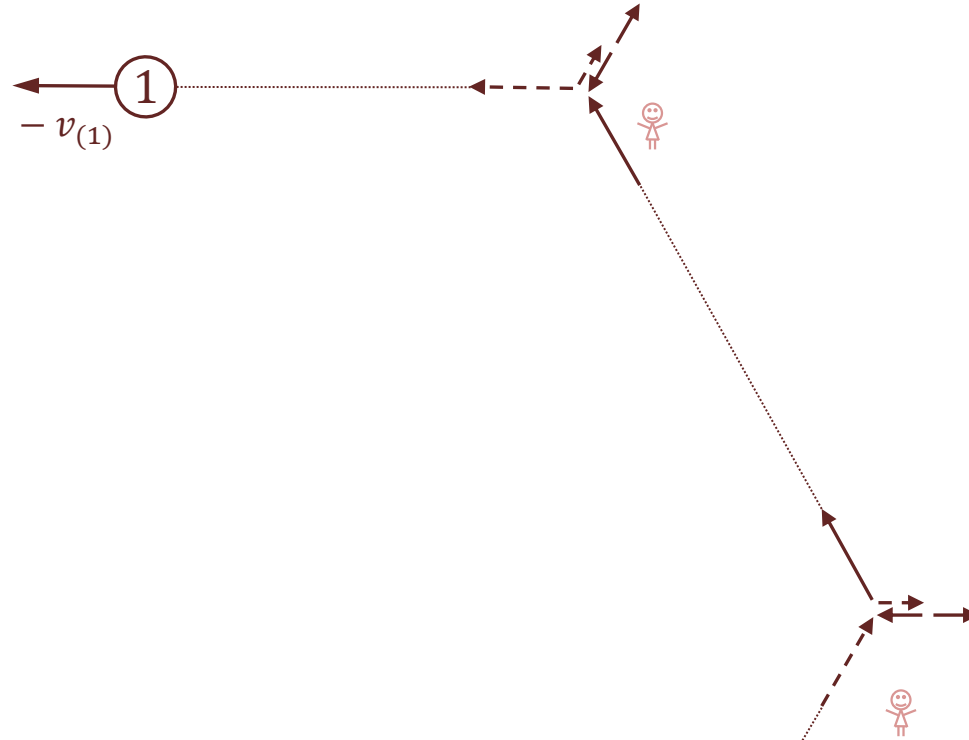


# Reversion Process

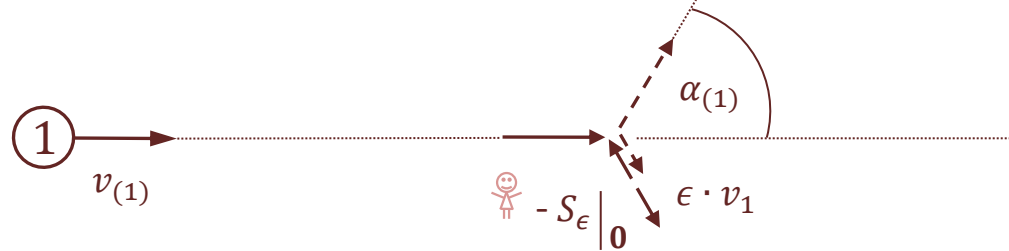
$$W_T * W_T$$



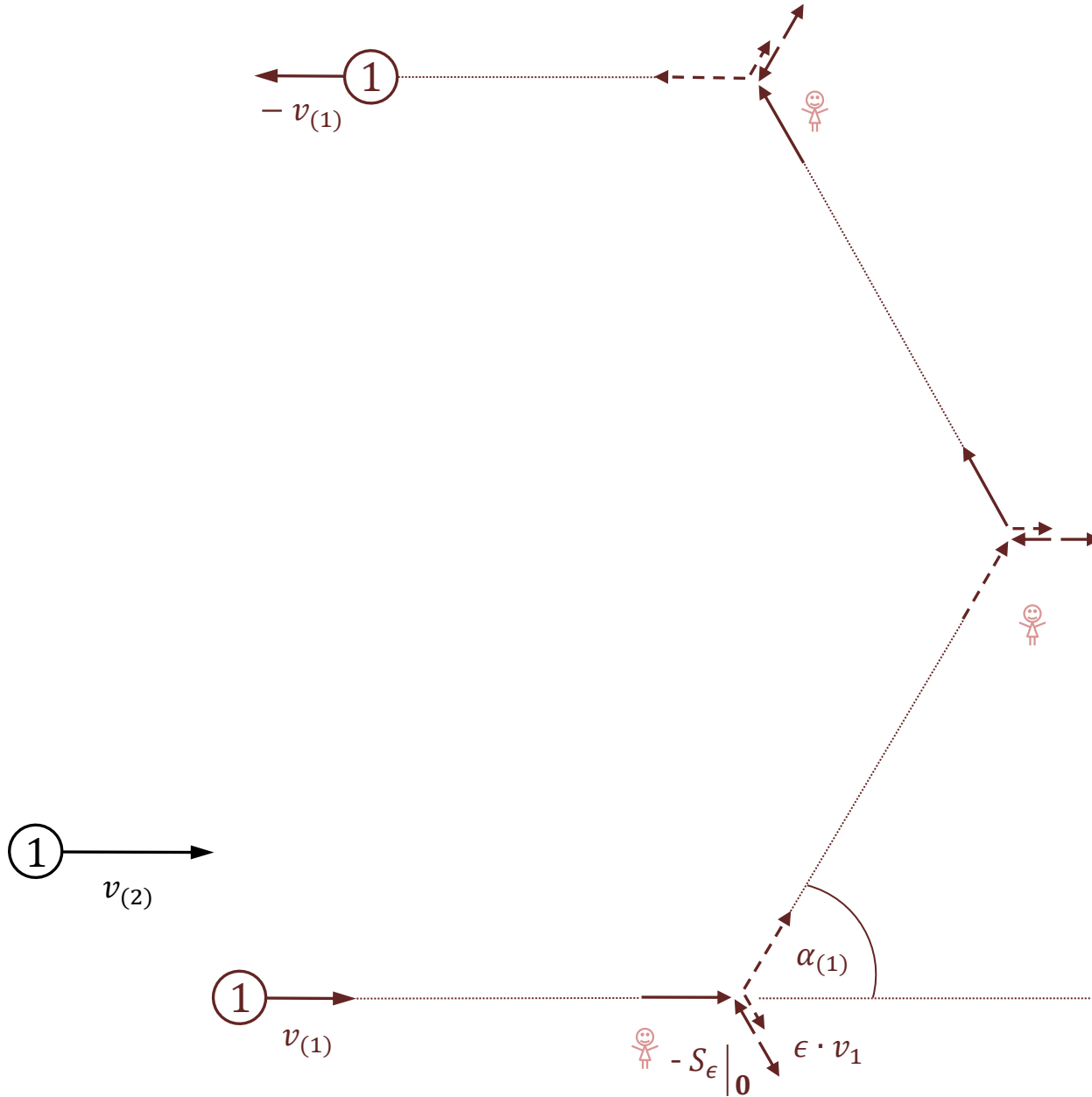
# Reversion Process



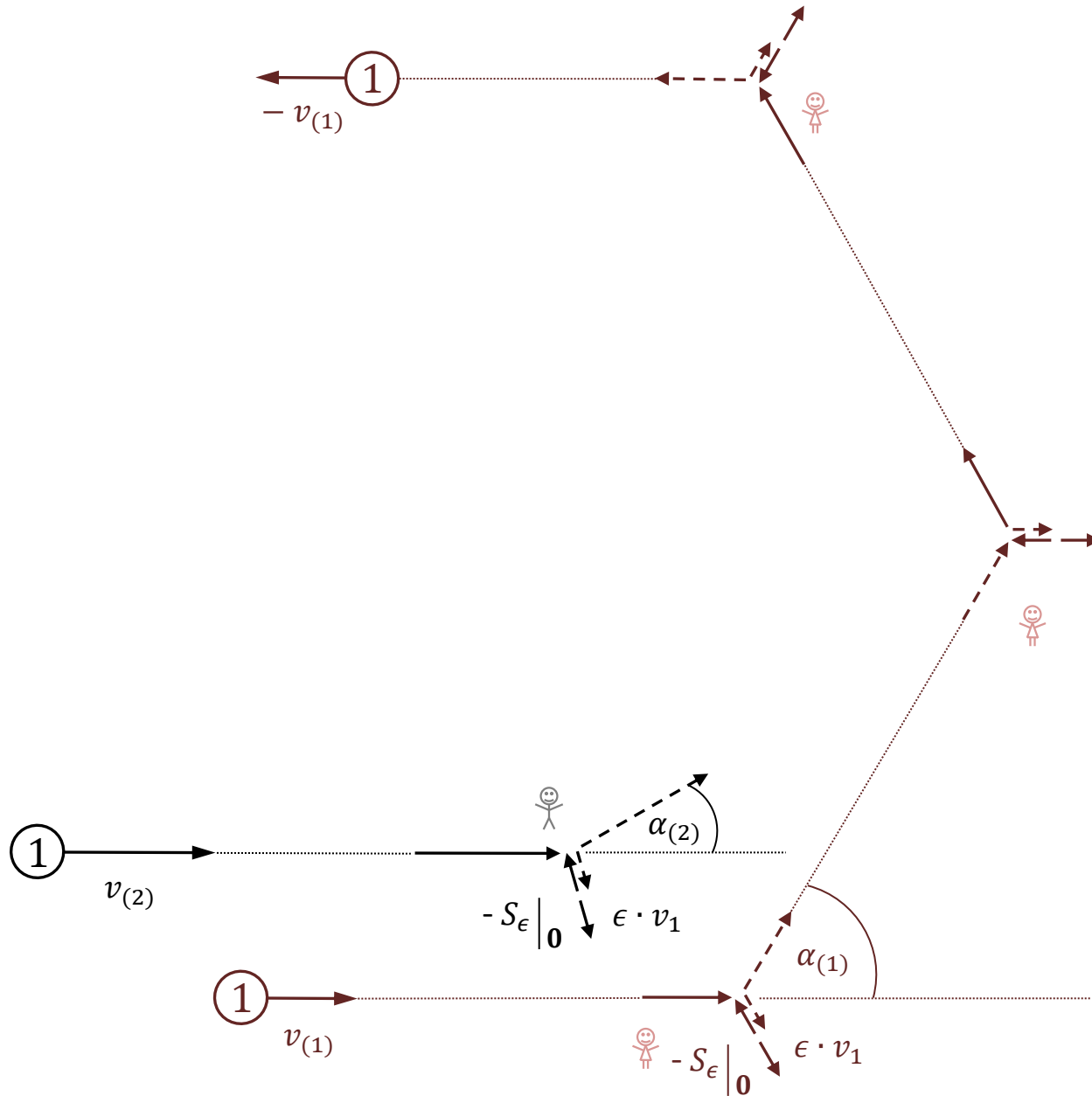
$$W_T * W_T * W_T$$



# Reversion Process

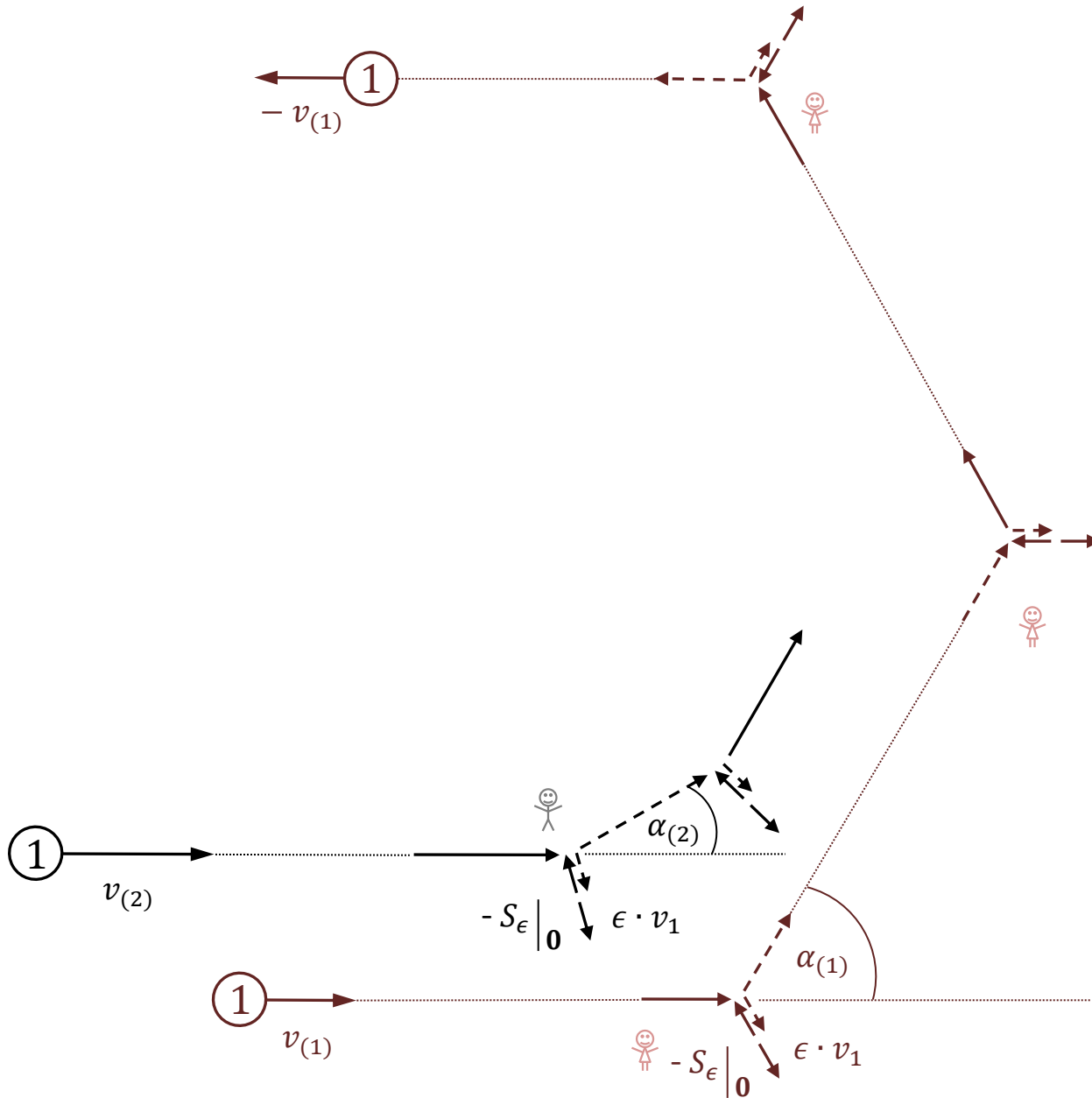


# Reversion Process

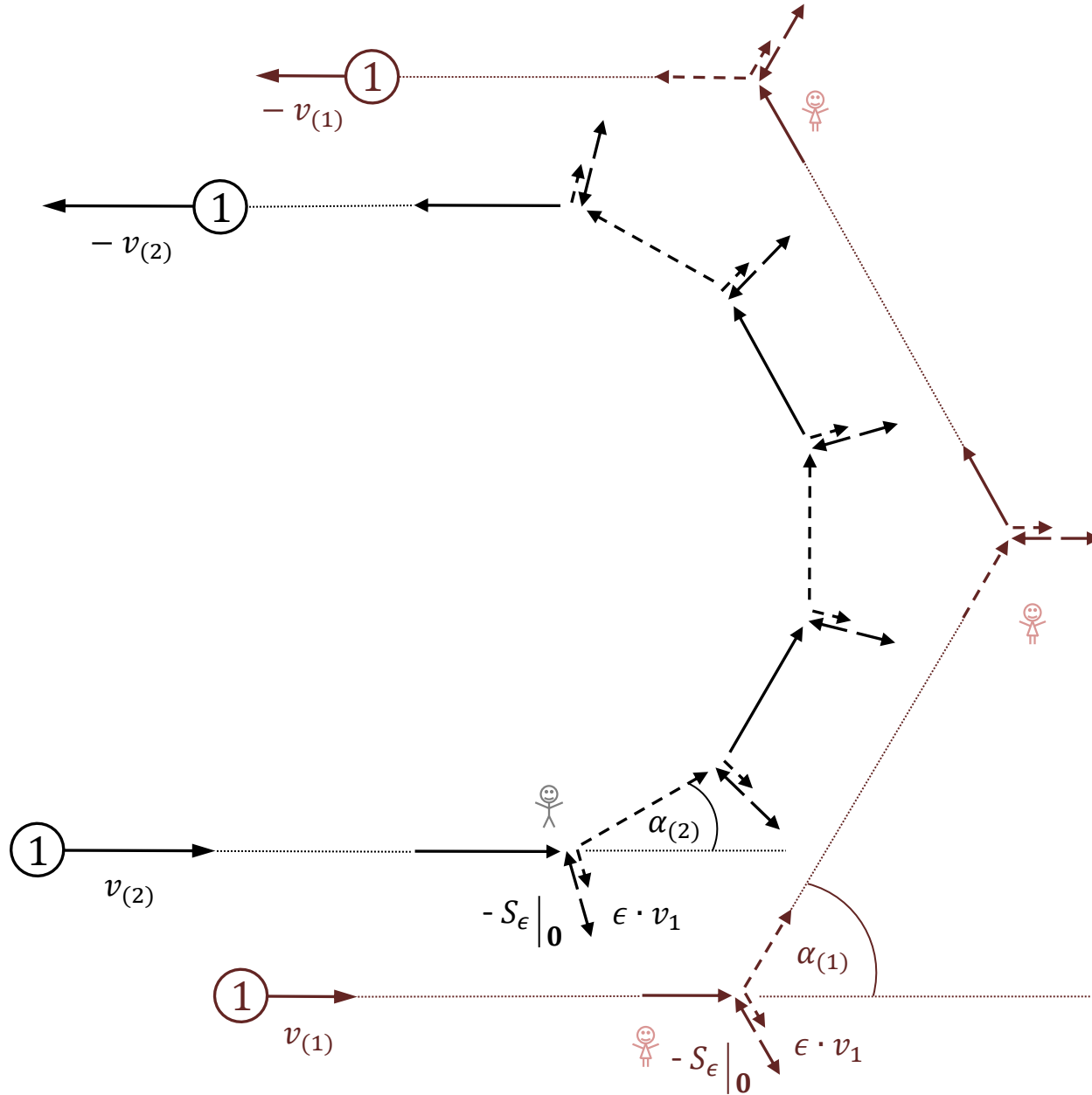




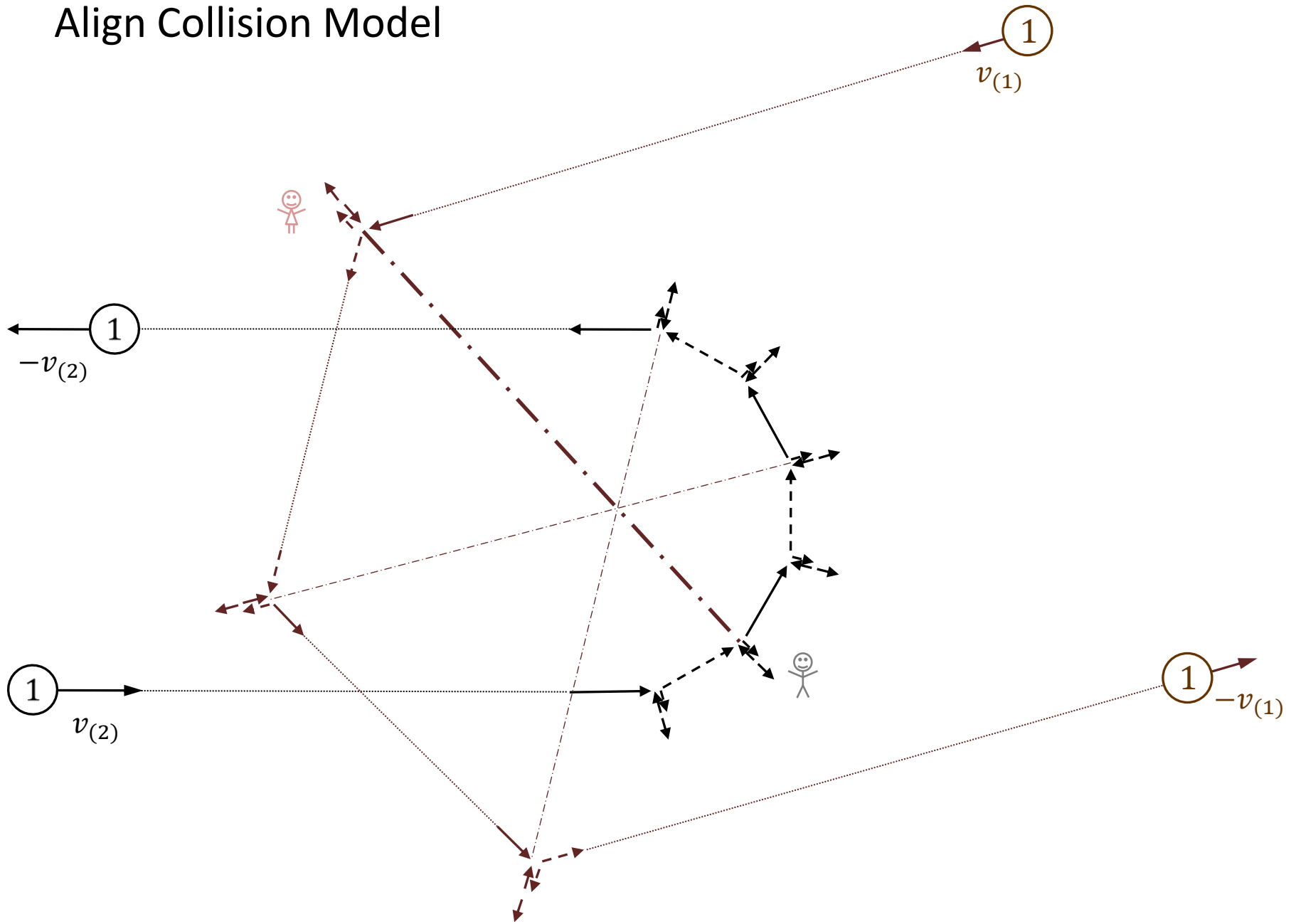
# Reversion Process



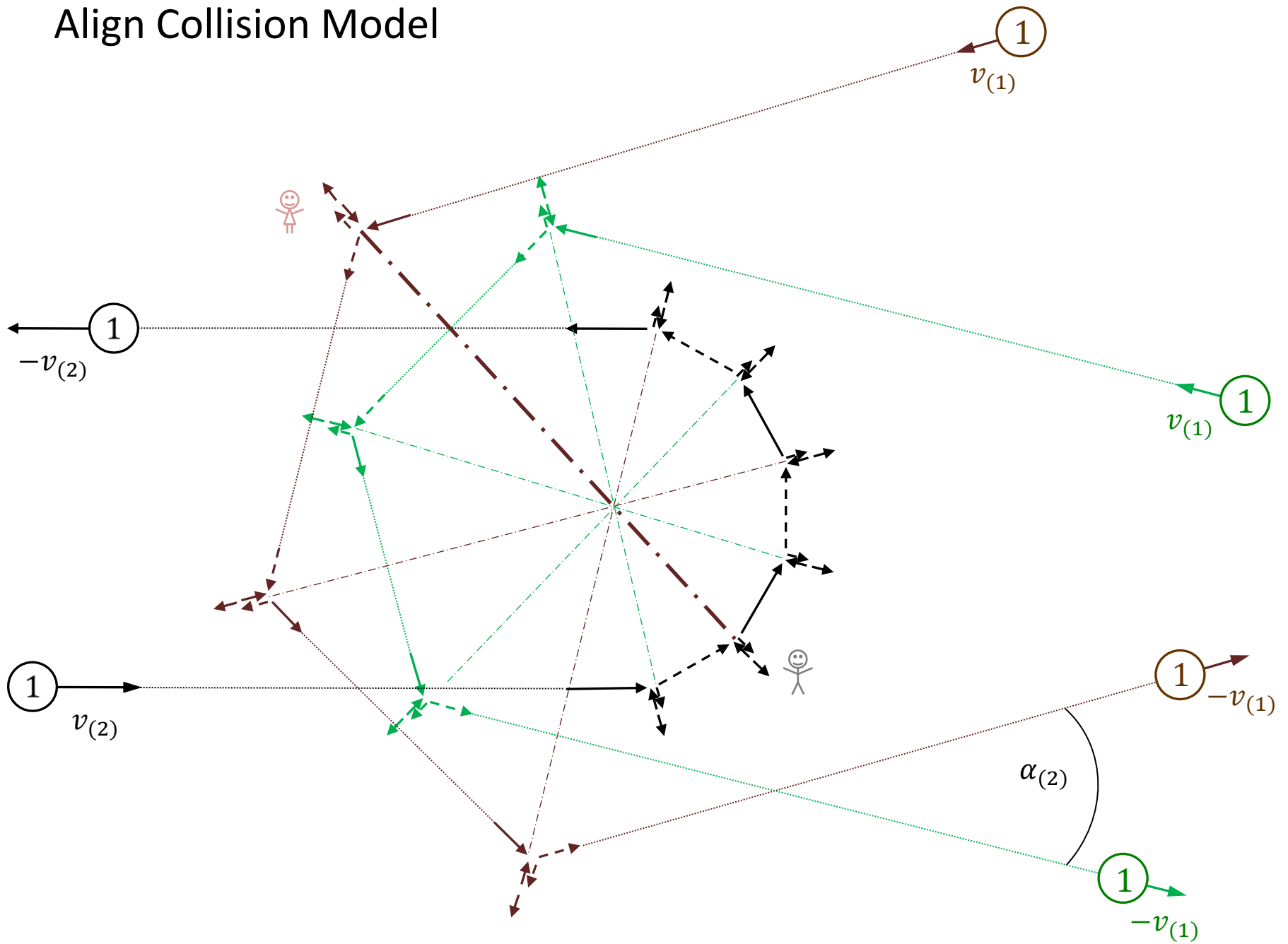
# Reversion Process



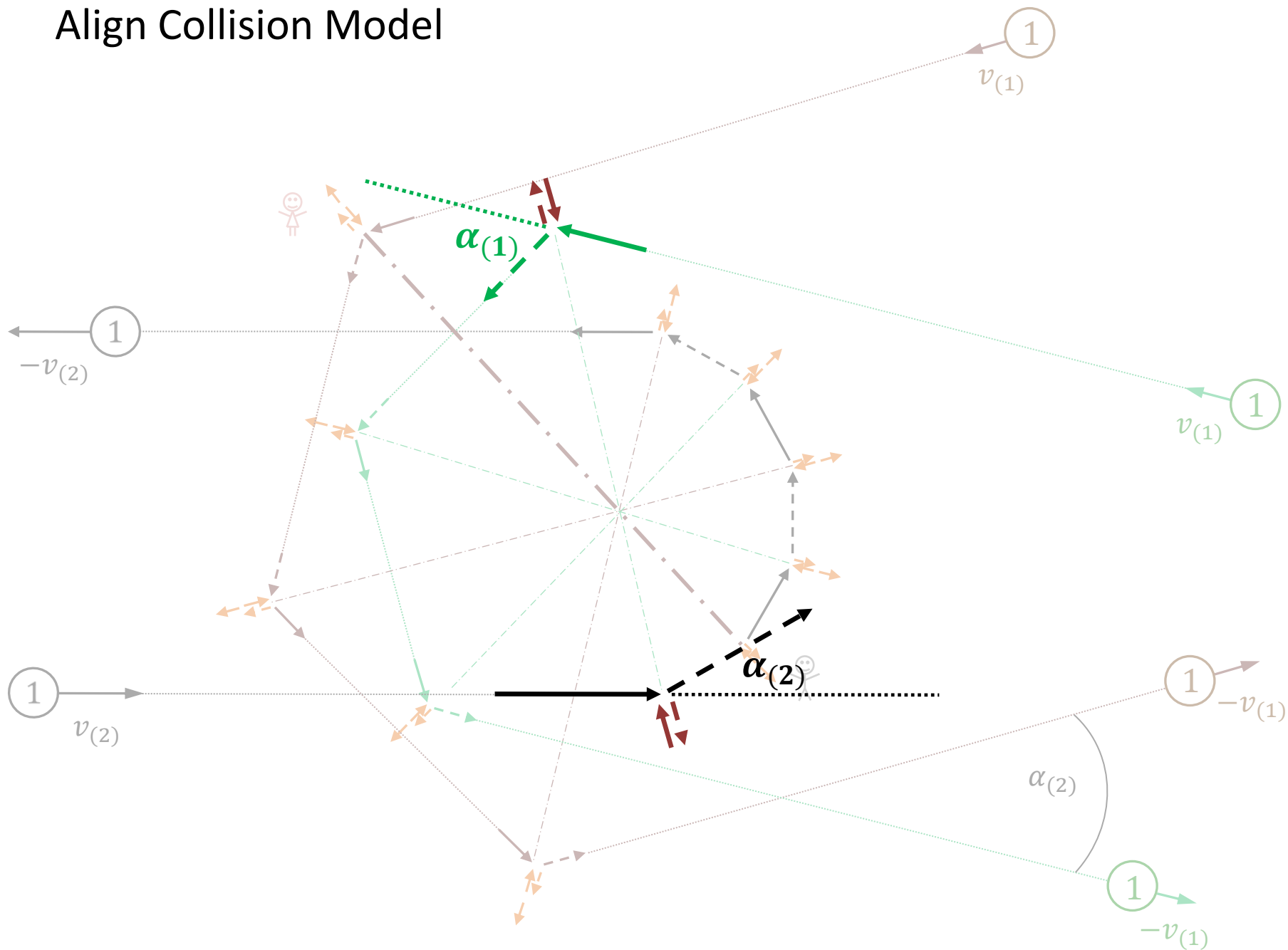
# Align Collision Model



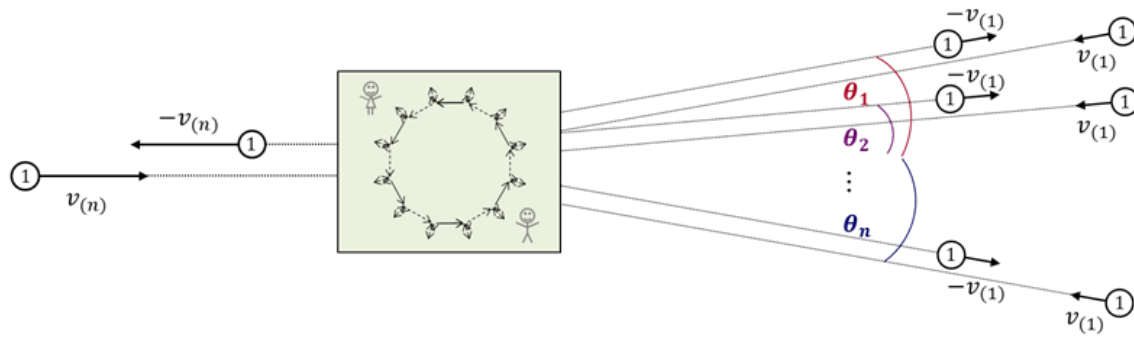
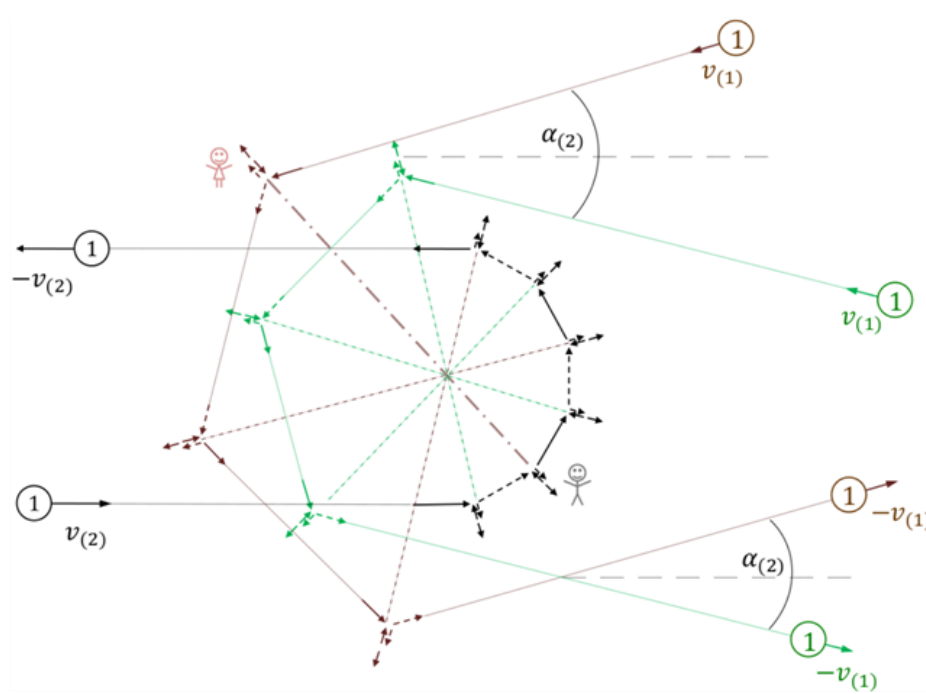
# Align Collision Model



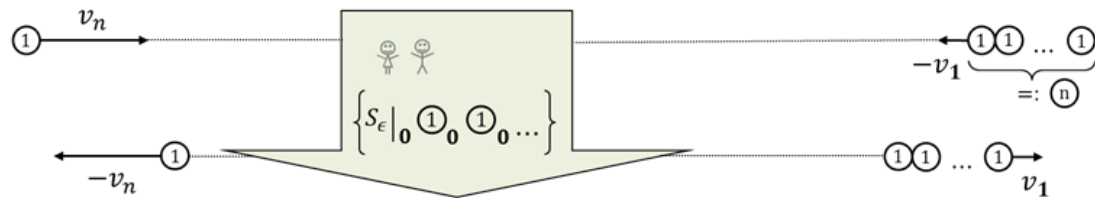
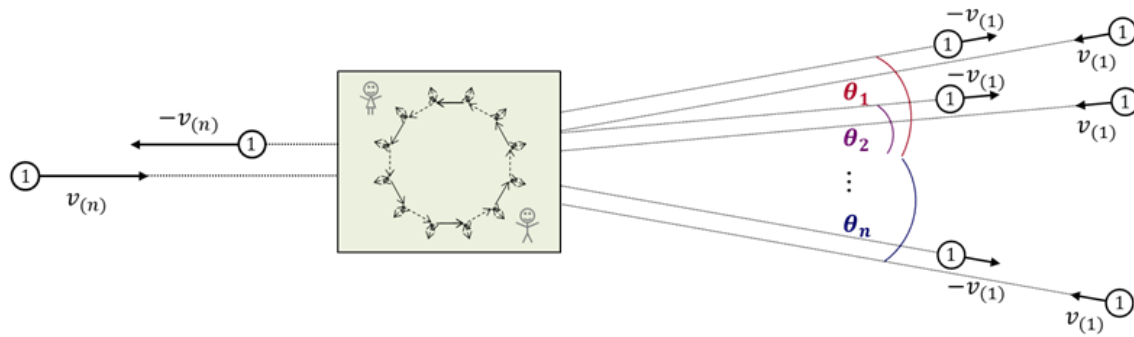
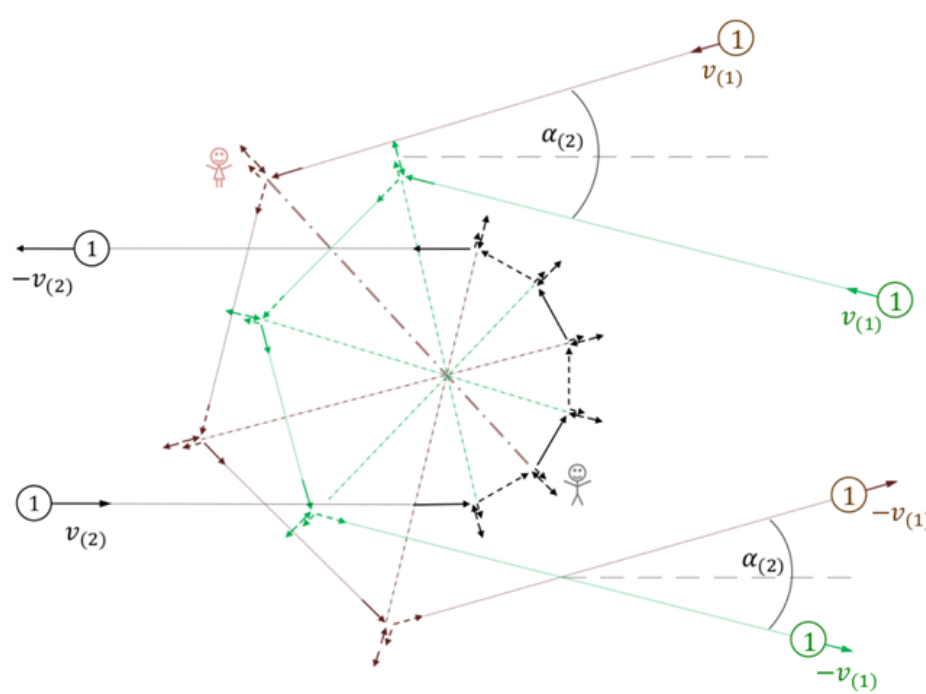
# Align Collision Model



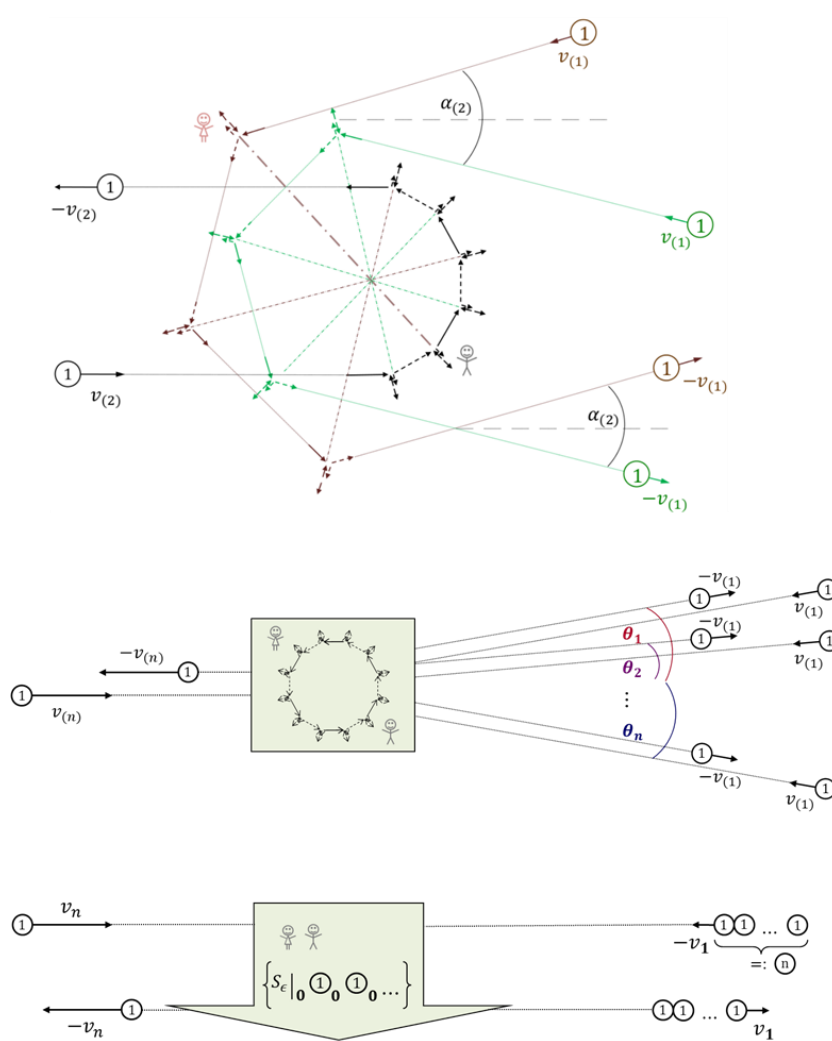
# Refinement



# Refinement



# Refinement

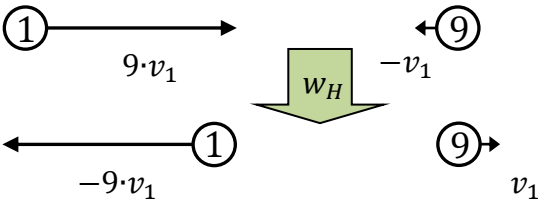


generic elastic collision

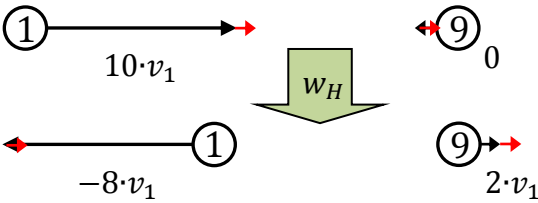
$$\textcircled{n} \mathbf{1} \cdot \mathbf{v}, \textcircled{1} \mathbf{-n} \cdot \mathbf{v} \implies \textcircled{n} \mathbf{-1} \cdot \mathbf{v}, \textcircled{1} \mathbf{n} \cdot \mathbf{v}$$



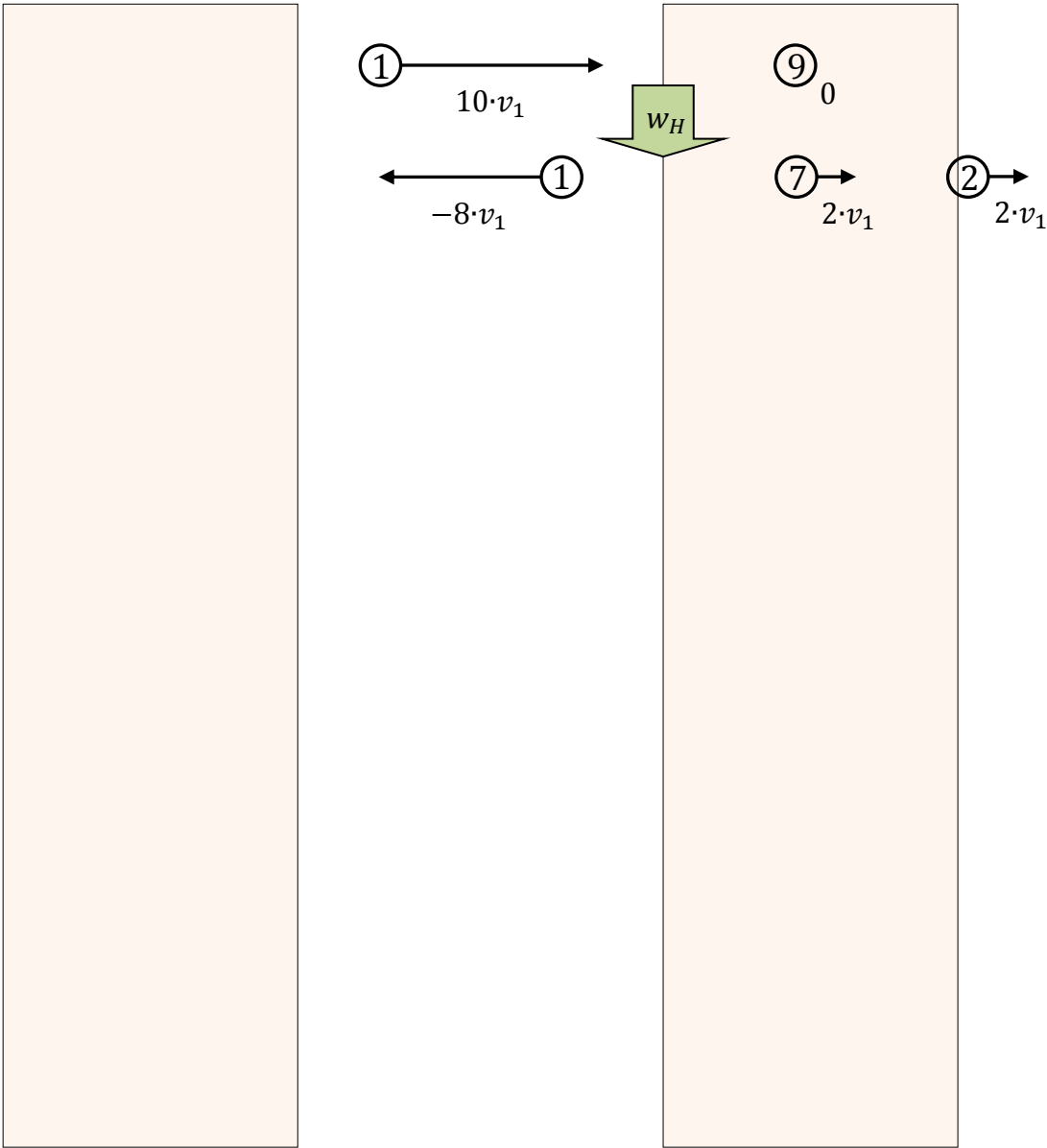
# Calorimeter Model



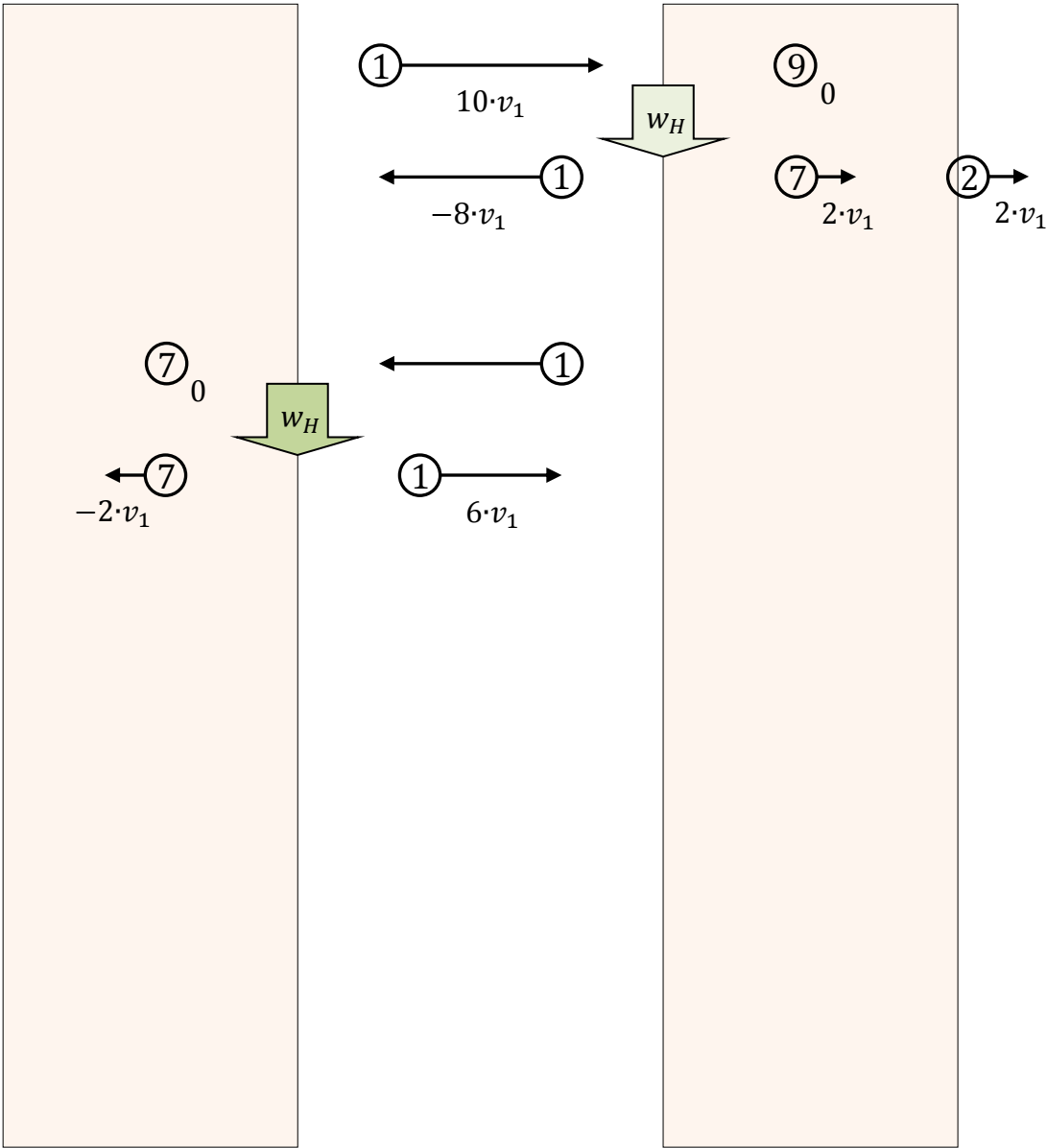
# Calorimeter Model



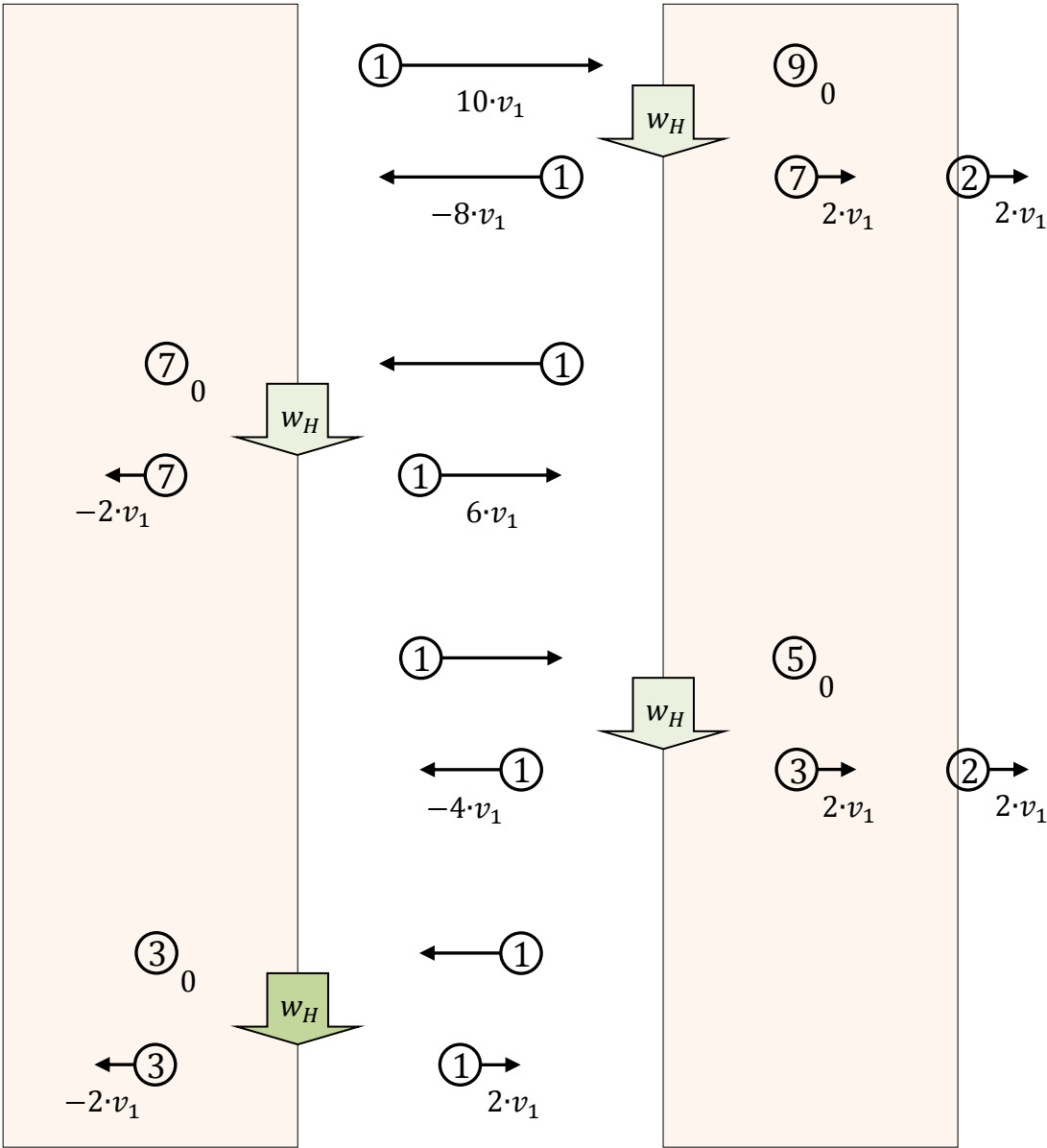
# Calorimeter Model

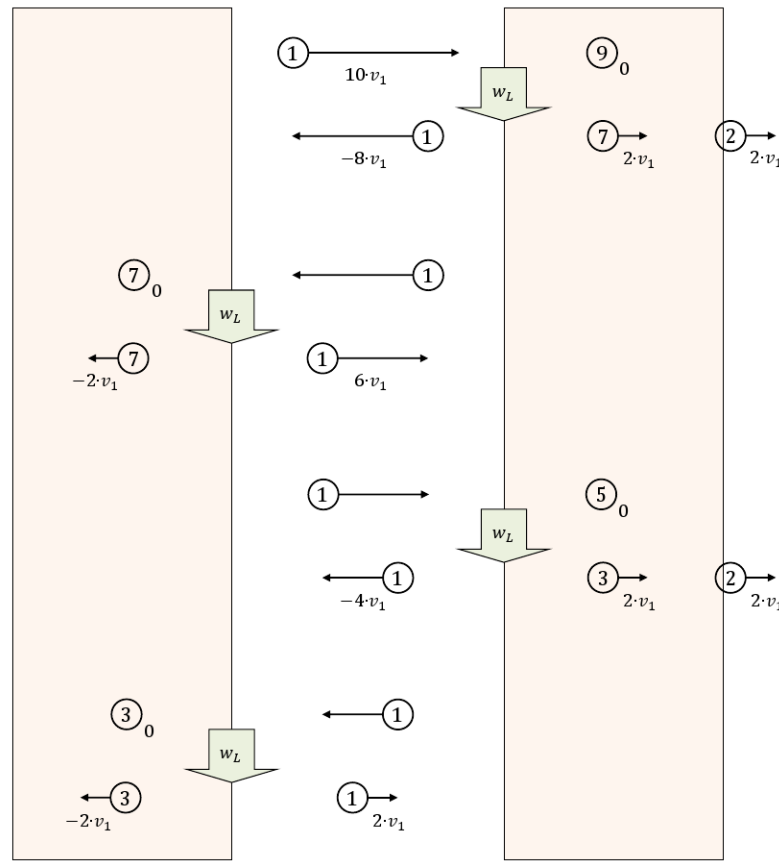


# Calorimeter Model



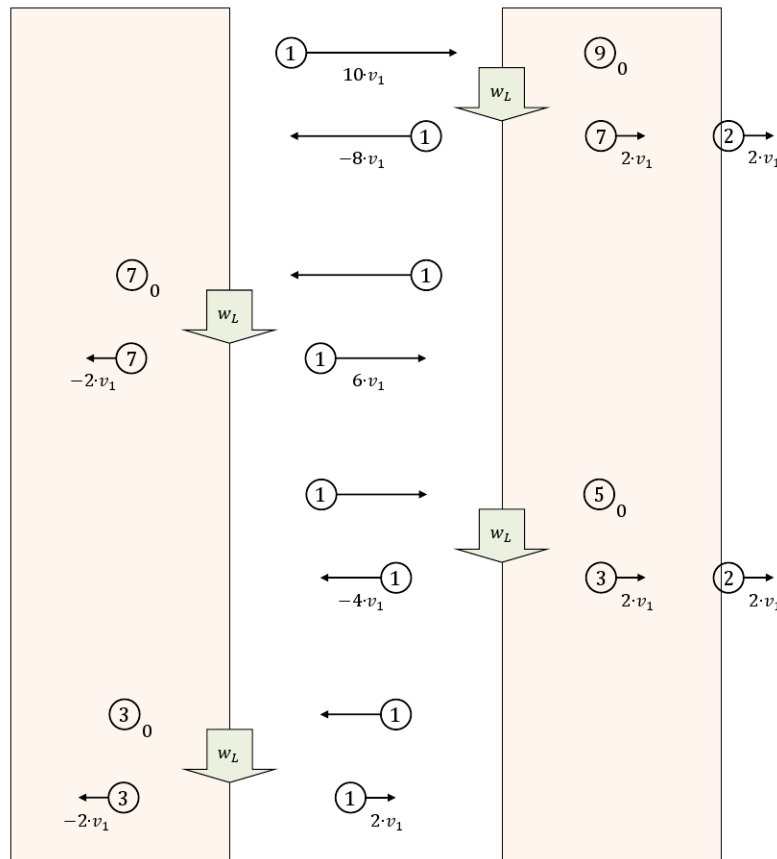
# Calorimeter Model





Total balance

$$\textcircled{1}_{10 \cdot \mathbf{v}}, 25 \cdot \textcircled{1}_0 \Rightarrow \textcircled{1}_0, \underbrace{10 \cdot \{ \textcircled{1}_{2 \cdot \mathbf{v}}, \textcircled{1}_{-2 \cdot \mathbf{v}} \}, 5 \cdot \textcircled{1}_{2 \cdot \mathbf{v}}}_{\text{calorimeter extract}}$$



Total balance

$$\textcircled{1}_{10 \cdot v} , 25 \cdot \textcircled{1}_0 \Rightarrow \textcircled{1}_0 , 10 \cdot \{ \textcircled{1}_{2 \cdot v} , \textcircled{1}_{-2 \cdot v} \} , 5 \cdot \textcircled{1}_{2 \cdot v}$$

$$\textcircled{1}_{16 \cdot v} , 64 \cdot \textcircled{1}_0 \Rightarrow \textcircled{1}_0 , 28 \cdot \{ \textcircled{1}_{2 \cdot v} , \textcircled{1}_{-2 \cdot v} \} , 8 \cdot \textcircled{1}_{2 \cdot v}$$

# Abstraction

Definition: *In an abstraction we regard the common quality of two empirical objects for itself without needing to consider the dissimilarity (in other regards).*



# Abstraction

Definition: In an abstraction we regard the common quality of two empirical objects for itself without needing to consider the dissimilarity (in other regards).

$\succ_l$  if two extended objects lie on top of each other: one will *cover* the other

$\succ_t$  if two processes begin simultaneously: one will *outlast* the other

$\succ_E$  if against the same system  $\{G_I\}$ : the effect of one source *exceeds* the other

$\succ_p$  in an head-on collision: one body *overruns* the other

$\succ_m := \succ_p \mid v_a = -v_b$

# Abstract Characterization

of reference objects

$$E[\textcircled{1}_{-v_1}, \textcircled{1}_{v_1}] = E[S_1|_0]$$

$$\mathbf{p}[S_1|_0] = 0$$

$$E[\textcircled{1}_{v_1}] = \frac{1}{2} \cdot E[S_1|_0]$$

$$\mathbf{p}[\textcircled{1}_{v_1}]$$

of calorimeter extract

$$\textcircled{a}_{v_a} \sim_{E, \mathbf{p}} k \cdot S_1|_0, l \cdot \textcircled{1}_{v_1}$$

# Quantification

$$E [ \textcircled{a}_{v_a} ] \stackrel{\text{(Equip.)}}{=} E [ S_1 | \mathbf{0} * \cdots * S_1 | \mathbf{0} ] \stackrel{\text{(Congr.)}}{=} E \cdot E [ S_1 | \mathbf{0} ]$$

# Quantification

$$E [ \textcircled{a}_{v_a} ] \stackrel{\text{(Equip.)}}{=} E [ S_1 | \mathbf{0} * \cdots * S_1 | \mathbf{0} ] \stackrel{\text{(Congr.)}}{=} E \cdot E [ S_1 | \mathbf{0} ]$$

$$\mathbf{p} [ \textcircled{a}_{v_a} ] \stackrel{\text{(Perp.Mob.)}}{=} \mathbf{p} [ \textcircled{1}_{v_1} * \cdots * \textcircled{1}_{v_1} ] \stackrel{\text{(Congr.)}}{=} \mathbf{p} \cdot \mathbf{p} [ \textcircled{1}_{v_1} ]$$

$$m [ \textcircled{a} ] \stackrel{\text{(Galilei)}}{=} m [ \textcircled{1} * \cdots * \textcircled{1} ] \stackrel{\text{(Congr.)}}{=} m \cdot m [ \textcircled{1} ]$$

$$\mathbf{v}_a =: \mathbf{v} \cdot \mathbf{v}_1$$

# Quantity Equations

count congruent units

$$\#\{S_1|_0\} \quad \#\{\textcircled{1}\} \quad \#\{\textcircled{1}_{v_1}\} \quad \#\{\boldsymbol{v}_1\}$$

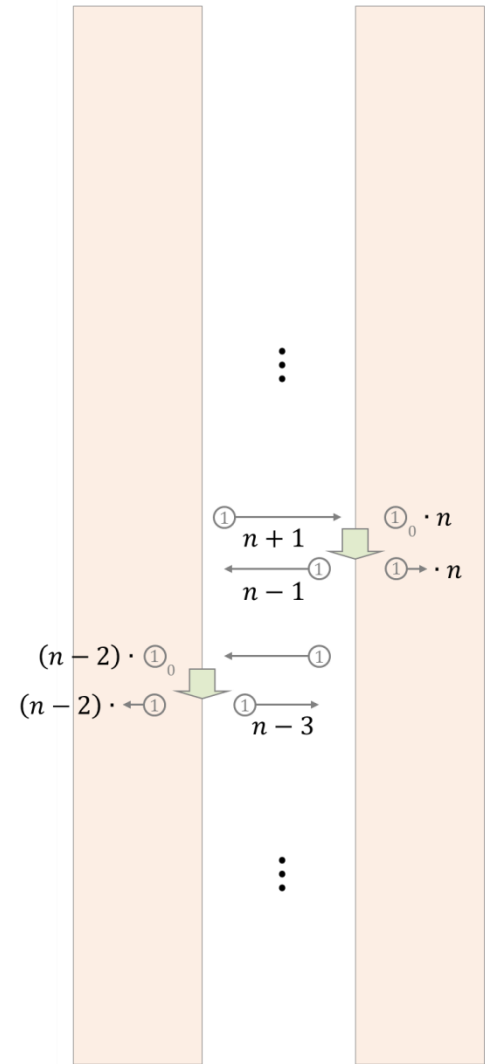
# Quantity Equations

count congruent units

$$\#\{S_1|_0\} \quad \#\{\textcircled{1}\} \quad \#\{\textcircled{1}_{v_1}\} \quad \#\{v_1\}$$

in Galilei-kinematics accumulate

$$(n - 2) \cdot \textcircled{1}_{-v_1} \quad , \quad n \cdot \textcircled{1}_{v_1} \quad \Delta v = 4 \cdot v_1$$



# Quantity Equations

count congruent units

$$\#\{S_1|_0\} \quad \#\{\textcircled{1}\} \quad \#\{\textcircled{1}_{v_1}\} \quad \#\{\mathbf{v}_1\}$$

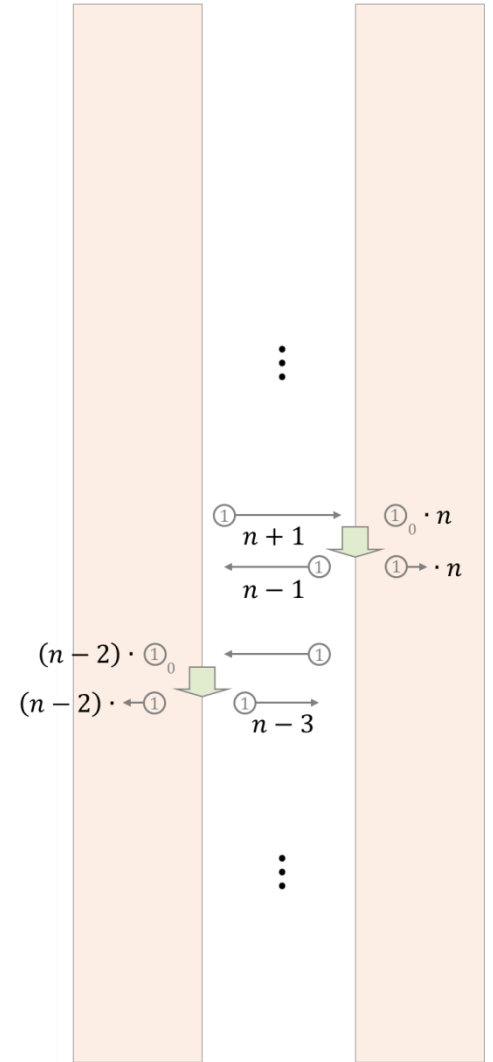
in Galilei-kinematics accumulate

$$(n-2) \cdot \textcircled{1}_{-v_1} \quad , \quad n \cdot \textcircled{1}_{v_1} \quad \Delta v = 4 \cdot v_1$$

derive (tailored) quantity equations

$$\left\{ \frac{E [\textcircled{a}_{v_a}]}{E [S_1|_0]} \right\} = \frac{1}{2} \cdot \left\{ \frac{m [\textcircled{a}_{v_a}]}{m [\textcircled{1}_{v_1}]} \right\} \cdot \left\{ \frac{v_a}{v_1} \right\}^2$$

$$\left\{ \frac{\mathbf{p} [\textcircled{a}_{v_a}]}{\mathbf{p} [\textcircled{1}_{v_1}]} \right\} = \left\{ \frac{m [\textcircled{a}_{v_a}]}{m [\textcircled{1}_{v_1}]} \right\} \cdot \left\{ \frac{\mathbf{v}_a}{\mathbf{v}_1} \right\}$$



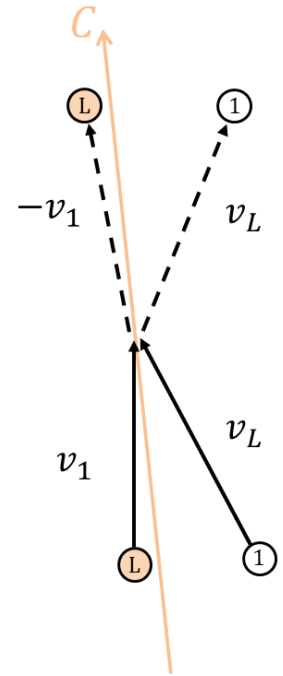
# Quantity Equations

count congruent units

$$\#\{S_1|_0\} \quad \#\{\textcircled{1}\} \quad \#\{\textcircled{1}_{v_1}\} \quad \#\{v_1\}$$

in Poincare-kinematics

$$\frac{v_L}{\sqrt{1 - \frac{v_L^2}{c^2}}} = L \cdot \frac{v_1}{\sqrt{1 - \frac{v_1^2}{c^2}}}$$



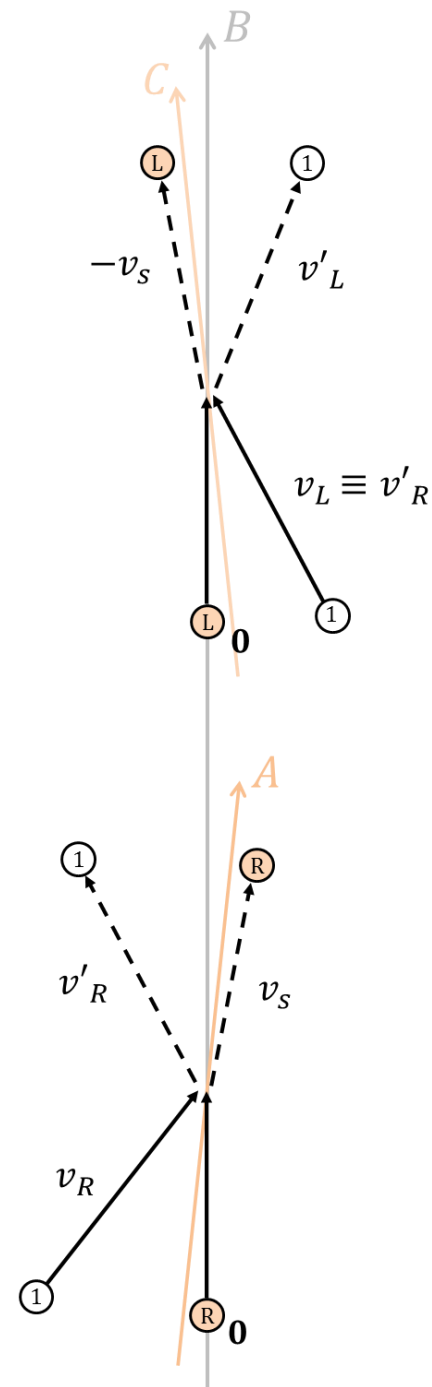


# Quantity Equations

count congruent units

$$\#\{S_1|_0\} \quad \#\{\textcircled{1}\} \quad \#\{\textcircled{1}_{v_1}\} \quad \#\{v_1\}$$

in Poincare-kinematics



# Quantity Equations

count congruent units

$$\#\{S_1|_0\} \quad \#\{\textcircled{1}\} \quad \#\{\textcircled{1}_{v_1}\} \quad \#\{\mathbf{v}_1\}$$

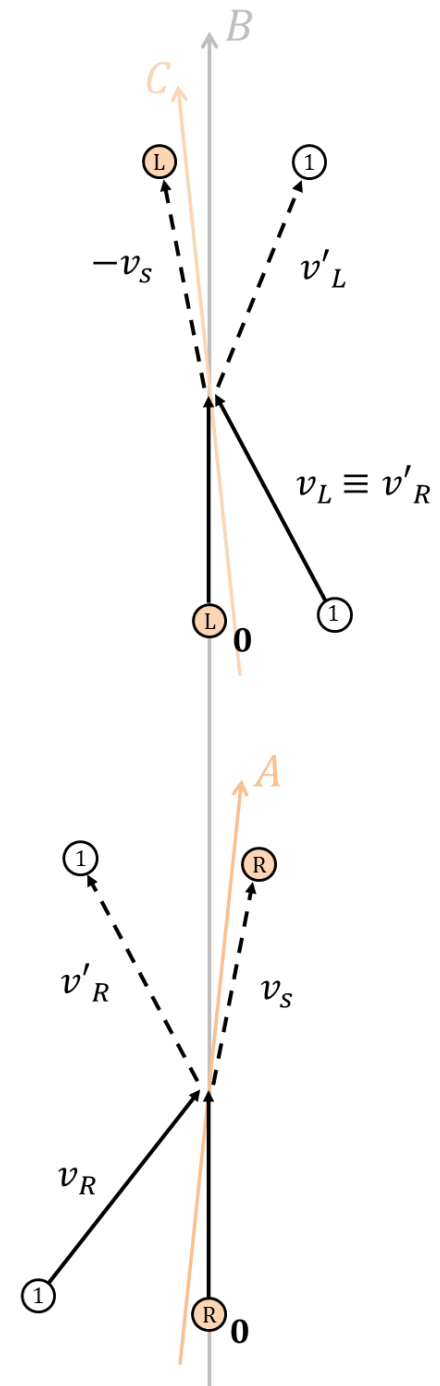
in Poincare-kinematics integrate

$$L \cdot \textcircled{1}_{-v_s} \quad , \quad R \cdot \textcircled{1}_{v_s} \quad \Delta v = v'_L - v_R$$

derive quantity equations

$$E[\textcircled{a}_{v_a}] = \{m \cdot c^2 \cdot (\gamma - 1)\} \cdot E[S_1|_0]$$

$$\mathbf{p}[\textcircled{a}_{v_a}] = \{\gamma \cdot m \cdot \mathbf{v}\} \cdot \mathbf{p}[\textcircled{1}_{v_1}]$$



# Measurement and Steering *Tool*

elementary standard interaction



eccentric elastic collision

$$w_1^{-1} * w_1$$



transversal kick

$$w_T := (w_1^{-1} * w_1)^{(B)}$$



generic head-on collision

$$w_H := w_T * \dots * w_T$$



absorption in calorimeter

$$W_{\text{cal}} := w_L^{(A)} * w_L^{(B)} * \dots$$



# Measurement and Steering *Tool*

elementary standard interaction



eccentric elastic collision

$$w_1^{-1} * w_1$$



transversal kick

$$w_T := (w_1^{-1} * w_1)^{(B)}$$



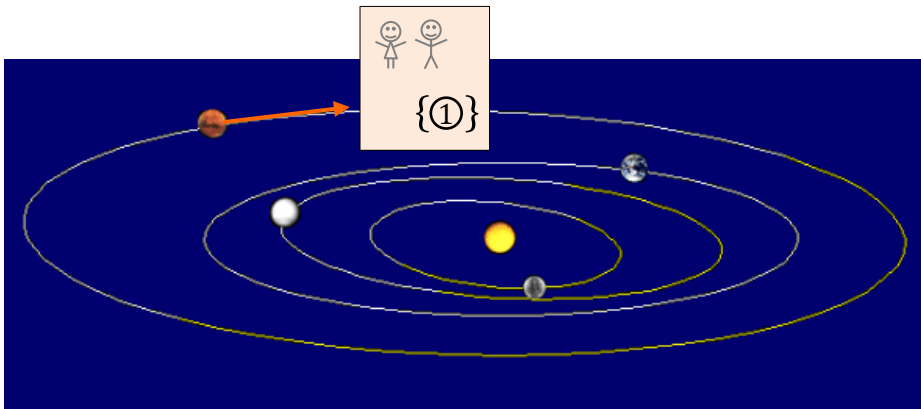
generic head-on collision

$$w_H := w_T * \dots * w_T$$

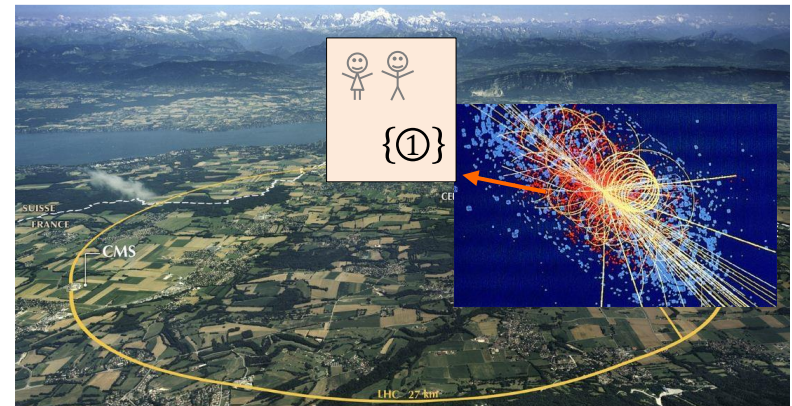


absorption in calorimeter

$$W_{cal} := w_L^{(A)} * w_L^{(B)} * \dots$$



gravitational interaction



nuclear interaction

# Physical Principles

*Principle of Causality*

*Principle of Inertia*

*Impossibility of a Perpetuum Mobile*

*Principle of Sufficient Reason*

*Relativity Principle*

*Superposition Principle*

# Methodical Principles

*Basic measurement:* as doubling of physical measures

*Congruence Principle:* for reliable quantification

*Equipollence Principle:* of measuring the cause of an action by its effect

# Methodical Principles

*Basic measurement:* as doubling of physical measures

*Congruence Principle:* for reliable quantification

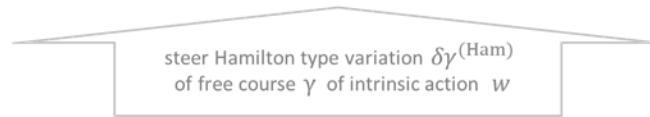
*Equipollence Principle:* of measuring the cause of an action by its effect



# Development

$$0 < \delta S_{\text{Ham}}[\gamma]$$

Principle of Least Action  
(external steering effort)



derived physical quantities & EOM

$$V_{\text{pot}}[x_I \rightarrow x'_I] := V_{\text{pot}}[\gamma] / \text{mod } \gamma \quad F_i := \frac{\Delta p_i}{\Delta t} [w|_{x_I, v_I}] / \text{mod } v_I \quad m_i \cdot \frac{d^2 s_i}{dt^2} [w|_{x_I, v_I}] = -\nabla^{(i)} V_{\text{pot}} \quad \forall i \in I$$



$$E = \frac{1}{2} \cdot m \cdot v^2$$

$$\mathbf{p} = m \cdot \mathbf{v}$$

quantity equations

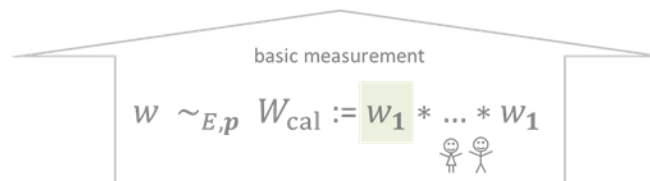


quantified observable

$$E [\textcircled{a}_{v_a}] = E \cdot E [S_1|0]$$

$$\mathbf{p} [\textcircled{a}_{v_a}] = \mathbf{p} \cdot \mathbf{p} [\textcircled{1}_{v_1}]$$

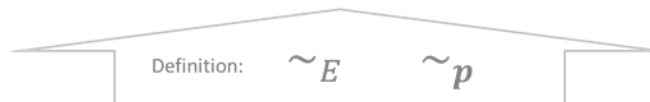
physical quantities



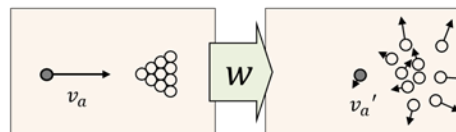
basic observable

$$E [\textcircled{a}_{v_a}]$$

$$\mathbf{p} [\textcircled{a}_{v_a}]$$



empirical basis





## Planck - *Wege zur physikalischen Erkenntnis*, 1944

'The axiomatic way of thinking is useful and necessary but therein also hides the dubious danger of one-sidedness, that the physical world view loses its meaning and degenerates into an empty formalism. Because if the connection with reality is detached then a physical law appears - not anymore as relation between quantities which can all be measured independently from one another but - *as a definition*, by means of which one of those quantities is reduced to the others. Such *reinterpretation* is particularly tempting because a physical quantity can be defined much more exactly by an equation than by a *measurement*; however that fundamentally represents *abandonment of its true meaning*.'