### Gröbner bases and cocyclic Hadamard matrices

### Álvarez, Armario, Falcón, Frau and Gudiel

University of Seville

5th Workshop on Real and Complex Hadamard Matrices and Applications







2 Cocyclic advantages







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### Hadamard cocyclic ideals

Hadamard ideals - Kotsireas, Koukouvinos, Seberry (2006)



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*G* is a group of order 4*t*, a *cocycle*  $\psi$  over *G* is a mapping  $\psi : G \times G \rightarrow \langle -1 \rangle$  satisfying  $\psi(1,1) = \psi(g,1) = \psi(1,g) = 1$ ,  $g \in G$  and the cocycle equation:

 $\psi(g_i,g_j) \ \psi(g_ig_j,g_k)\psi(g_i,g_jg_k) \ \psi(g_j,g_k) = 1, \quad g_i,g_j,g_k \in G.$ (1)



### Pros & Cons

 $\mathsf{Pros}$ 

• Faster Hadamard test



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Image: A matrix

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- Search performed in terms of a basis of cocyles

 $\{\mathsf{coboundaries}\} \cup \{\mathsf{inflation}\} \cup \{\mathsf{transgression}\}$ 



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Cons

• { Cocyclic Hadamard Matrices }  $\subset$  { Hadamard Matrices }



### The idea

Use the Algebraic Geometry artillery (namely Gröbner basis techniques) to determine both the cardinality and the elements of the set  $\mathcal{H}_G$  of cocyclic Hadamard matrices over a multiplicative finite group G of 4t elements.



# First (naive) approach

 $\mathbb{Q}[X_G]$  be the polynomial ring over  $\{X_G\} = \{x_{i,j}: g_i, g_j \in G\}$ 



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# First (naive) approach

 $\mathbb{Q}[X_G]$  be the polynomial ring over  $\{X_G\} = \{x_{i,j}: g_i, g_j \in G\}$ 

#### Theorem

The set  $\mathcal{H}_G$  can be identified with the set of zeros of the zero-dimensional ideal  $I_G = I_G^1 + I_G^2 + I_G^3 + I_G^4 \subset \mathbb{Q}[X_G]$ , where

$$\left\{ \begin{array}{l} I_{G}^{1} = \langle x_{i,j}^{2} - 1 \colon i, j \in G \rangle \\ I_{G}^{2} = \langle x_{i,j} x_{ij,k} - x_{j,k} x_{i,jk} \colon i, j, k \in G \rangle \\ I_{G}^{3} = \langle x_{1,j} - 1, x_{i,1} - 1 \colon i, j \in G \setminus \{1\} \rangle \\ I_{G}^{4} = \langle \sum_{j \in G} x_{i,j} \colon i \in G \setminus \{1\} \rangle \end{array} \right.$$



Set of polynomials defining  $I_G$ :

 $O(t^3)$  polynomials of degree up to 2 over  $O(t^2)$  variables



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Image: Image:

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Open computer algebra system for polynomial computations SINGULAR CocGM(t, G, opt)



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Open computer algebra system for polynomial computations SINGULAR CocGM(t, G, opt)http://personales.us.es/raufalgan/LS/hadamard.lib

$$\begin{cases} G = 1 \Rightarrow \mathbb{Z}_t \times \mathbb{Z}_2^2, G = 2 \Rightarrow D_{4t} \\ opt = 1 \Rightarrow \sharp \mathcal{H}_G, opt = 2 \Rightarrow \mathcal{H}_G \end{cases}$$

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 $t \leq 3$ 

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### Basis of normalized cocycles

Fixed a representative cocycle  $\rho$ , and a basis for normalized cocycles **B**.  $\mathbb{Q}[X]$  be the polynomial ring over  $\{X\} = \{x_i: i \in \{1, \dots, k\}\}$ 



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#### Theorem

(Álvarez et al. )[2008] The matrix  $M_{\psi}$  is Hadamard if and only if the vector of coordinates  $(x_1, \ldots, x_k)_{\mathbf{B}}$  of  $\psi$  with regards to **B** satisfies the following system of 4t - 1 equations and k unknowns

$$\begin{cases}
(m_{2,1}^{1})^{x_{1}} \dots (m_{2,1}^{k})^{x_{k}} + \dots + (m_{2,4t}^{1})^{x_{1}} \dots (m_{2,4t}^{k})^{x_{k}} &= 0 \\
\vdots & \vdots \\
(m_{4t,1}^{1})^{x_{1}} \dots (m_{4t,1}^{k})^{x_{k}} + \dots + (m_{4t,4t}^{1})^{x_{1}} \dots (m_{4t,4t}^{k})^{x_{k}} &= 0
\end{cases}$$
(2)

The set  $\mathcal{H}_{G}^{\rho}$  can be identified with the set of zeros of the following zero-dimensional ideal of  $\mathbb{Q}[X]$ .

$$J_G := \langle x_i^2 - x_i \colon i \in \{1, \ldots, k - m\} \rangle + \langle \sum_{h=1}^{4t} s_{I,h}(X) \colon I \in \{1, \ldots, 4t - 1\} \rangle.$$

s(l, h) is defined in terms of paths and intersections, and  $deg(s_{l,h}) \leq 2$ .



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$$t \leq 7, D_{4t}$$

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Fine tuning:  $\mathbb{Z}_t \times \mathbb{Z}_2^2$ 

Diagrammatic properties:

CocAH(t, col, dist, H)



Gudiel

Gröbner bases ...

Fine tuning:  $\mathbb{Z}_t \times \mathbb{Z}_2^2$ 

Diagrammatic properties:

CocAH(t, col, dist, H)

{ col: parity of columns
 dist: sum of each row
 H: fixed values of some coordinates



Gudiel

t = 31



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t = 31

col: 0, 4, 2, 4, 2, 2, 2, 2, 0, 2, 2, 0, 4, 2, 2



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t = 31

col: 0, 4, 2, 4, 2, 2, 2, 2, 0, 2, 2, 0, 4, 2, 2

dist: 12, 18, 18, 12



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t = 31

col: 0, 4, 2, 4, 2, 2, 2, 2, 0, 2, 2, 0, 4, 2, 2

dist: 12, 18, 18, 12

H = 14, 15, 21, 24, 29



t = 31

col: 0, 4, 2, 4, 2, 2, 2, 2, 0, 2, 2, 0, 4, 2, 2

dist: 12, 18, 18, 12

H = 14, 15, 21, 24, 29

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# Fine tuning: $D_{4t}$



Gudiel

Gröbner bases ..

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### Fine tuning: $D_{4t}$

CocDH(t, col, dist, H)



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CocDH(t, col, dist, H)

dist: number of new intersections in each row [2,t]
 H: fixed values of some coordinates



t = 31



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Image: A matrix

t = 31

 $\mathsf{dist}\ 1, 1, 2, 2, 3, 3, 2, 3, 0, 1, 0, 4, 2, 2, 3, 2, 3, 2, 2, 0, 0, 3, 1, 1, 2, 1, 3, 2, 2, 3$ 



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t = 31

dist 1, 1, 2, 2, 3, 3, 2, 3, 0, 1, 0, 4, 2, 2, 3, 2, 3, 2, 2, 0, 0, 3, 1, 1, 2, 1, 3, 2, 2, 3

 $H = \underline{5}, \underline{6}, \underline{17}, \underline{36}, \underline{48}, 63, 64, \underline{84}, \underline{95}, 115, \underline{117}$ 



t = 31

 $\mathsf{dist}\ 1, 1, 2, 2, 3, 3, 2, 3, 0, 1, 0, 4, 2, 2, 3, 2, 3, 2, 2, 0, 0, 3, 1, 1, 2, 1, 3, 2, 2, 3$ 

H = 5, 6, 17, 36, 48, 63, 64, 84, 95, 115, 117

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### Future work



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### Future work

Improve the quality of the helping information



to get better results !



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# Thank you and farewell !!!





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