Asymptotic and Constructive Bounds for Covering Arrays

Charles J. Colbourn¹ with Erin Lanus and Kaushik Sarkar

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Covering Arrays

Covering Array. Definition

- Let N, k, t, and v be positive integers.
- Let C be an N × k array with entries from an alphabet Σ of size v; we typically take Σ = {0,..., v − 1}.
- ▶ When (ν_1, \ldots, ν_t) is a *t*-tuple with $\nu_i \in \Sigma$ for $1 \le i \le t$, (c_1, \ldots, c_t) is a tuple of *t* column indices $(c_i \in \{1, \ldots, k\})$, and $c_i \ne c_j$ whenever $\nu_i \ne \nu_j$, the *t*-tuple $\{(c_i, \nu_i) : 1 \le i \le t\}$ is a *t*-way interaction.
- The array *covers* the *t*-way interaction {(*c_i*, ν_i) : 1 ≤ *i* ≤ *t*} if, in at least one row ρ of C, the entry in row ρ and column *c_i* is ν_i for 1 ≤ *i* ≤ *t*.
- Array C is a covering array CA(N; t, k, v) of strength t when every t-way interaction is covered.
- ► CAN(t, k, v) is the minimum N for which a CA(N; t, k, v) exists.

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Covering Array CA(13;3,10,2)

0	0	0	0	0	0	0	0	0	0	
1	1	1	1	1	1	1	1	1	1	
1	1	1	0	1	0	0	0	0	1	
1	0	1	1	0	1	0	1	0	0	
1	0	0	0	1	1	1	0	0	0	
0	1	1	0	0	1	0	0	1	0	
0	0	1	0	1	0	1	1	1	0	
1	1	0	1	0	0	1	0	1	0	
0	0	0	1	1	1	0	0	1	1	
0	0	1	1	0	0	1	0	0	1	
0	1	0	1	1	0	0	1	0	0	
1	0	0	0	0	0	0	1	1	1	
0	1	0	0	0	1	1	1	0	1	

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The Motivating Questions

- 1. How precisely can we determine CAN(t, k, v)?
- 2. When we can show $CAN(t, k, v) \le N$, can we construct a CA(N; t, k, v) efficiently and explicitly?

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A Random Method

- Fix t and v independent of k.
- In an array chosen uniformly at random from {0,..., v − 1}^{N×k}, the probability that any specific *t*-way interaction is not covered is (1 − ¹/_{v^t})^N.
- ► So the expected number of uncovered *t*-way interactions is $\binom{k}{t} v^t \left(1 \frac{1}{v^t}\right)^N$.
- When this expected number is less than 1, some array has all *t*-way interactions covered!

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Covering Arrays

A Random Method

► Take logarithms of
$$\binom{k}{t} v^t \left(1 - \frac{1}{v^t}\right)^N < 1$$
 to get

$$\mathsf{CAN}(t,k,v) \leq \frac{t}{\log \frac{v^t}{v^t-1}} \log k(1+\mathrm{o}(1))$$

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Derandomizing

The Stein-Lovász-Johnson Method

- Generate one row at a time at random from $\{0, \ldots, v-1\}^k$.
- The expected number of t-way interactions covered by this row for the first time is ¹/_{v^t} times the number of as-yet-uncovered t-way interactions.
- Stein (1974), Lovász (1975), and Johnson (1974): Select a row that covers the maximum number of as-yet-uncovered *t*-way interactions.
- But finding such a row is NP-hard!
- So select a row that covers at least the average.
- In fact, we do better: After each row is selected, the number of uncovered interactions is an integer. (Discrete SLJ)

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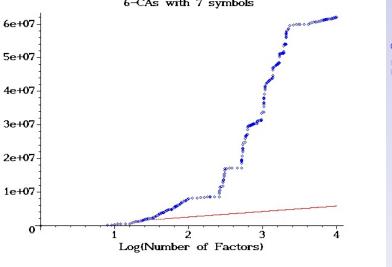
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Computational Results

6-CAs with 7 symbols



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Better asymptotics

- SLJ and Discrete SLJ do not account for the limited statistical dependence among the events of coverage of interactions.
- The (symmetric version of the) Lovász Local Lemma (LLL) yields a better bound (obtained by Godbole, Skipper, and Sunley in 1996)

$$\mathsf{CAN}(t,k,v) \leq \frac{t-1}{\log \frac{v^t}{v^t-1}} \log k(1+\mathrm{o}(1))$$

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Better asymptotics

Francetic-Stevens

 Francetic and Stevens (2016) made the first improvement in 20 years, using an entropy compression technique

$$\mathsf{CAN}(t,k,v) \leq \frac{v(t-1)}{\log\left(\frac{v^{t-1}}{v^{t-1}-1}\right)}\log k(1+\mathrm{o}(1))$$

Is it better? Use the Taylor series expansion to verify.

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- Applications require explicit constructions of arrays, not asymptotic bounds.
- Can we meet the bounds efficiently when t and v are fixed?
 - Discrete SLJ: Yes, an efficient conditional expectation method ("density") deterministically chooses a row as good as average (Bryce-C, 2007, 2009)
 - LLL: Yes if you allow expected polynomial time: Moser-Tardos (2010) give a resampling method that succeeds within a linear expected number of resamplings.
 - Francetic-Stevens: Not clear (yet), but stay tuned.

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Why are the tables so bad?

• When v = 7, t = 6, and k = 50 there are

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interactions to cover!

- Density stores coverage information for each, and the storage requirement is enormous.
- Moser-Tardos recomputes coverage for each for every resampling, and the number of resamplings needed is a random variable.

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Sample space reduction

- Consider covering arrays that are invariant under the action of a group on the symbols of the array, in order to make the space to search for an array much smaller.
- We consider three permutation groups acting on the symbols.
 - the cyclic group of order v, which partitions the interactions on t columns into v^{t-1} orbits of length v;
 - the Frobenius or affine group when v is a prime power, which partitions the interactions into $\frac{v^{t-1}-1}{v-1}$ orbits of length v(v-1) and one orbit of length v;
 - ► PGL when v + 1 is a prime power, which partitions the interactions into orbits of length v(v - 1)(v - 2), v(v - 1), and v.

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Covering Orbits

- Now we cover orbits of interactions and apply the group to recover the covering array at the end.
- We can apply the SLJ paradigm and the density methods in the same way in the cyclic and Frobenius cases (For density, see Colbourn 2013).
- We can apply LLL and the Moser-Tardos methods in the same way in the cyclic and Frobenius cases.
- This reduces time and storage for density, and time for Moser-Tardos — But what does it do to the asymptotic bounds?

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Better asymptotics Cyclic LLL

 Applying LLL with the cyclic group, we reproduce the Francetic and Stevens (2016) bound

$$\mathsf{CAN}(t,k,v) \leq \frac{v(t-1)}{\log\left(\frac{v^{t-1}}{v^{t-1}-1}\right)}\log k(1+o(1))$$

and we get a Moser-Tardos type method that runs in expected polynomial time to meet the bound.

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Better asymptotics Frobenius LLL

 Applying LLL with the Frobenius group, we improve on the Francetic and Stevens (2016) bound

$$\mathsf{CAN}(t, k, v) \le \frac{v(v-1)(t-1)}{\log\left(\frac{v^{t-1}}{v^{t-1}-v+1}\right)}\log k(1+o(1))$$

and we get a Moser-Tardos type method that runs in expected polynomial time to meet the bound.

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What about PGL?

- Covering orbits of length v can be done with v constant rows.
- ► Covering orbits of length v(v − 1)(v − 2) can be done with LLL (or Moser-Tardos).
- But orbits of length v(v 1) are a problem, in that their probability of being covered in a random selection is much smaller.
- So the road to higher levels of sharply ℓ-transitive groups acting on the symbols seems blocked.

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Covering Perfect Hash Families Setup I

- George Sherwood suggested a framework for constructing covering arrays using finite fields.
 - q a prime power,
 - \mathbb{F}_q the finite field of order q,

 - *T*_{t,q} the set of all nonzero column vectors of length t with entries from 𝔽_q.

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A vector x ∈ T_{t,q} is sometimes called a *permutation* vector.

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Covering Arrays

Covering Perfect Hash Families Setup II

Lemma

Let $\mathcal{X} = \{\mathbf{x}_1, \dots, \mathbf{x}_t\}$ be a set of vectors from $\mathcal{T}_{t,q}$. The array $A = (a_{ij})$ formed by setting a_{ij} to be the product of \mathbf{r}_i and \mathbf{x}_j is a CA(q^t ; t, t, q) if and only if the $t \times t$ matrix $X = [\mathbf{x}_1 \cdots \mathbf{x}_t]$ is nonsingular.

 This is essentially the Bose-Bush construction of orthogonal arrays.

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CPHFs and Covering Arrays

A covering perfect hash family CPHF(n; k, q, t) is an n × k array C = (c_{ij}) with entries from T_{t,q} so that, for every set {γ₁,..., γ_t} of distinct column indices, there is at least one row index ρ of C for which [c_{ργ1} ··· c_{ργ1}] is nonsingular; call this a *covering t-set* and say that the *t*-set of columns is *covered* in row ρ.

Lemma

Suppose that C is a CPHF(n; k, q, t). Then there exists a $CA(n(q^t - 1) + 1; t, k, q)$.

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Lemma

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CPHF Better Asymptotics for Covering Arrays

- ► Choose entries of an *n* × *k* array *A* uniformly at random from *T*_{t,q}.
- Let T be a set of t columns of A.
- Within one row of A, the probability that the columns of T are not covering is

$$\phi_{t,q} := 1 - rac{\prod_{i=0}^{t-1}(q^t - q^i)}{(q^t - 1)^t} = 1 - \prod_{i=1}^{t-1}rac{q^t - q^i}{q^t - 1}.$$

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► The probability that A does not contain a covering t-set for T is φⁿ_{t,q}. Asymptotic and Constructive Bounds for Covering Arrays

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Random Selection with Postprocessing

- Constructing an array with κ > k columns, we can compute the expected number of *t*-tuples of columns not covered.
- Choose κ so that the number of uncovered tuples of columns is κ k.
- Then delete one column from each uncovered tuple.
- At least k remain, and the result is a covering array!

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CPHF Better Asymptotics for Covering Arrays

Lemma For all $q \ge 3$ and $t \ge 3$,

$$\frac{1}{q} \leq \phi_{t,q} \leq \frac{q+1}{q^2}.$$

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Next Steps: The Binary Case

- The CPHF approach improves known bounds when v > 2, but what about the binary case?
- Here Hadamard matrices lead to many of the best known bounds.
- ► One can view permutation vectors as (specific) functions of *t* variables over 𝔽_q. The key is that we can determine the probability with which *t* such functions form a covering set.
- Can one find a set of t binary functions of s variables yielding improvements on the known bounds?
- It appears to me that Hadamard-type approaches are the appropriate methods here.

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